

*An Earth Observation Challenge:
2D+t and 3D+t dynamics of the
upper ocean*

*Satellite measurements of Ocean
Surface Current ?*

A necessary tool



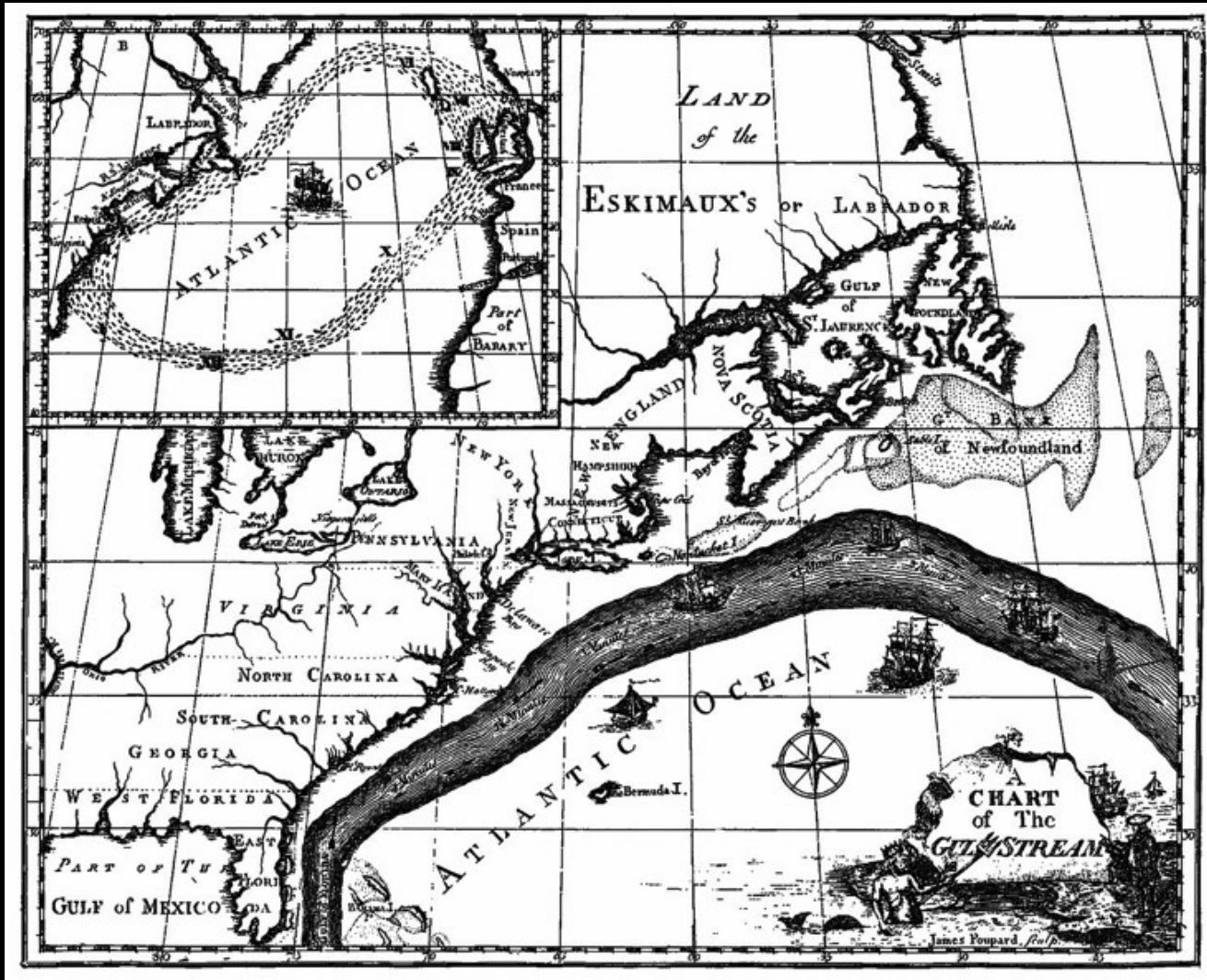
Essential needs

P. Niiler (2009) Oceanography in 2025

Oceanography of 2025 will require observations and realistic modeling of the circulation patterns that contain the vertical motion of the upper 200 m. Models will be compared not by how well they assimilate or replicate the sea level or reproduce the geostrophic velocity, but rather by how their internal vorticity and thermal energy and fresh water balances maintain ageostrophic velocity structures and the associated vertical circulations. This task calls for development and implementation of continued new methods and instruments for direct velocity observations of the oceans.

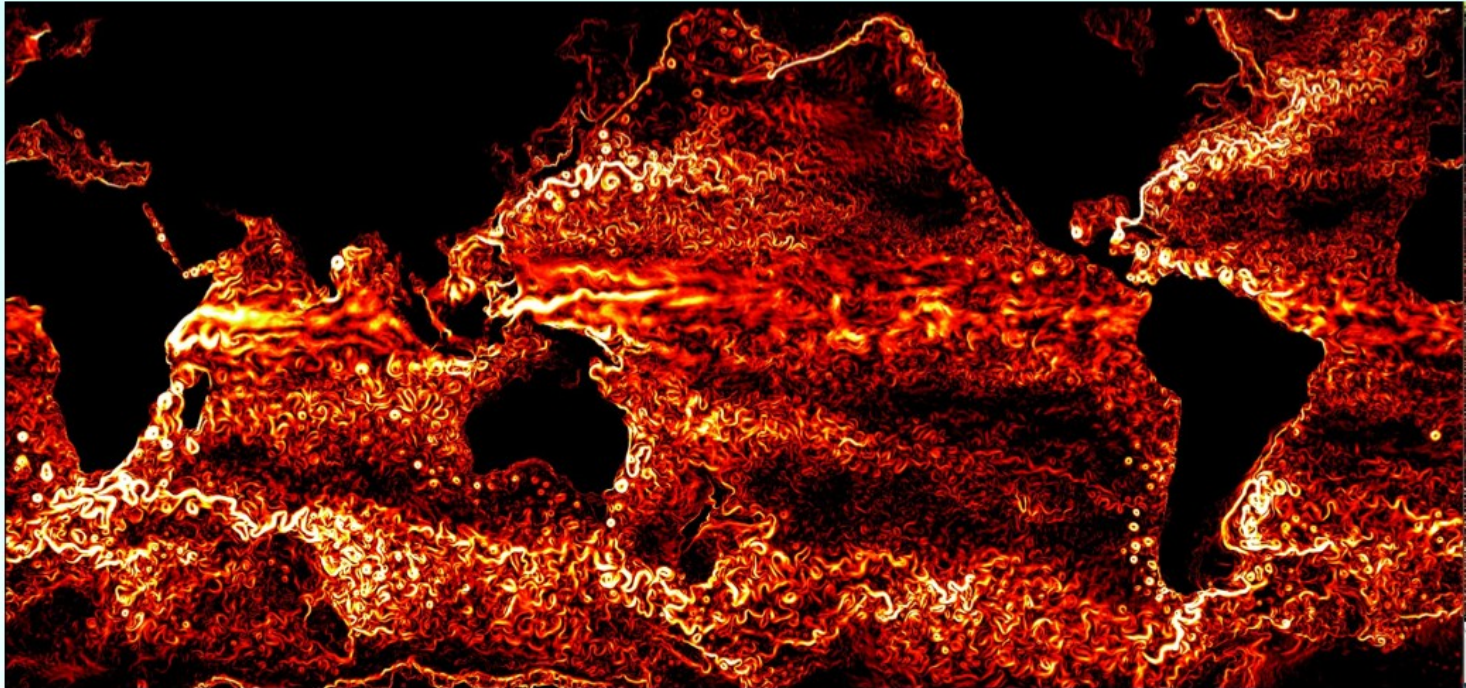


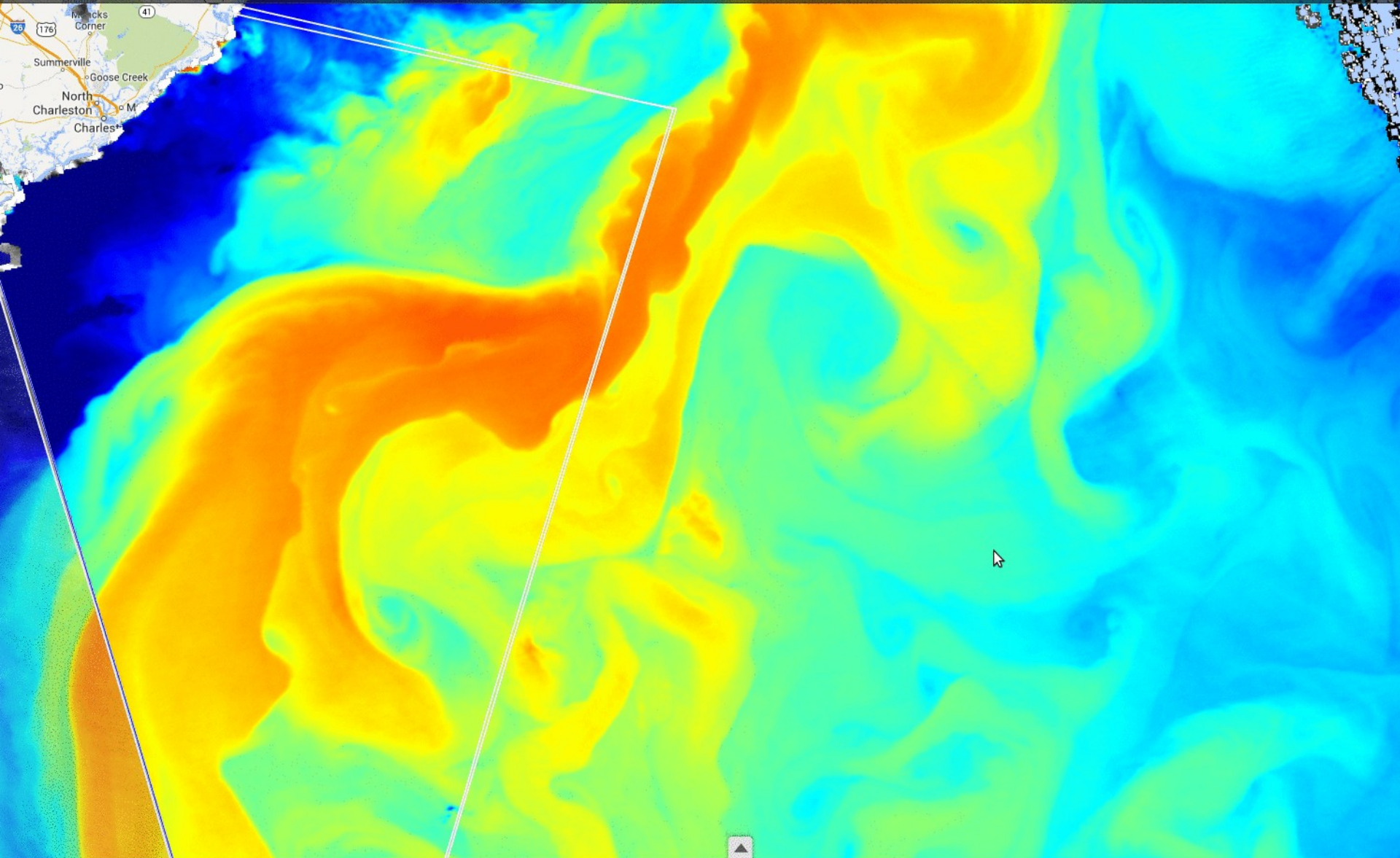
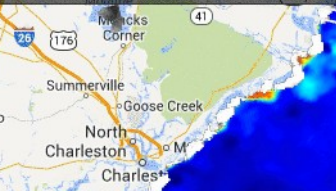
Initial Gulf Stream Depiction (circulated by Benjamin Franklin, circa 1770)



What do we model: A Fully Turbulent Ocean !

All the oceans are crowded with a large number of mesoscale eddies (>100 km). This vision has been confirmed by modelling studies (OFES, POP - 2003) with a 1/10th degree resolution performed on the ES



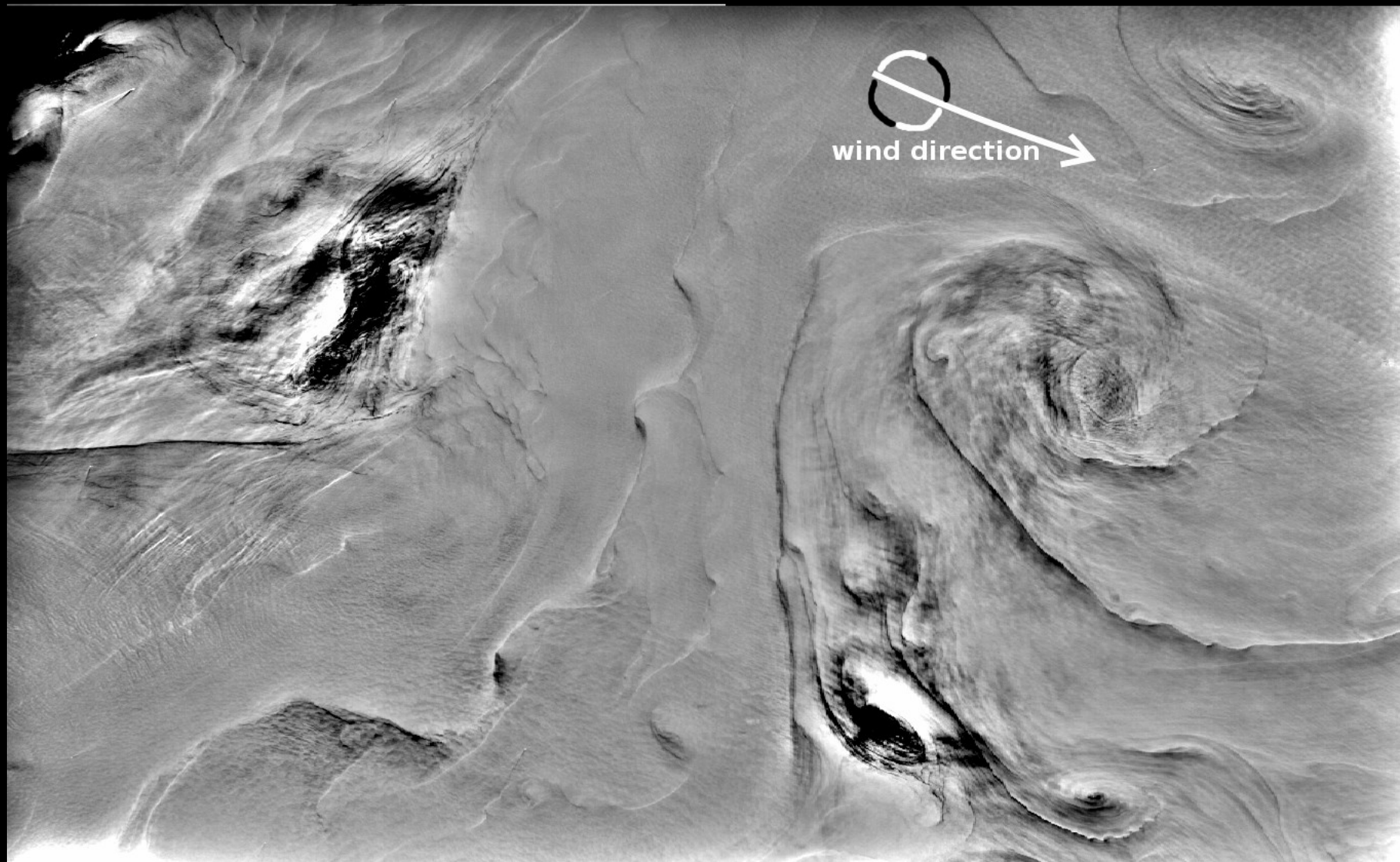


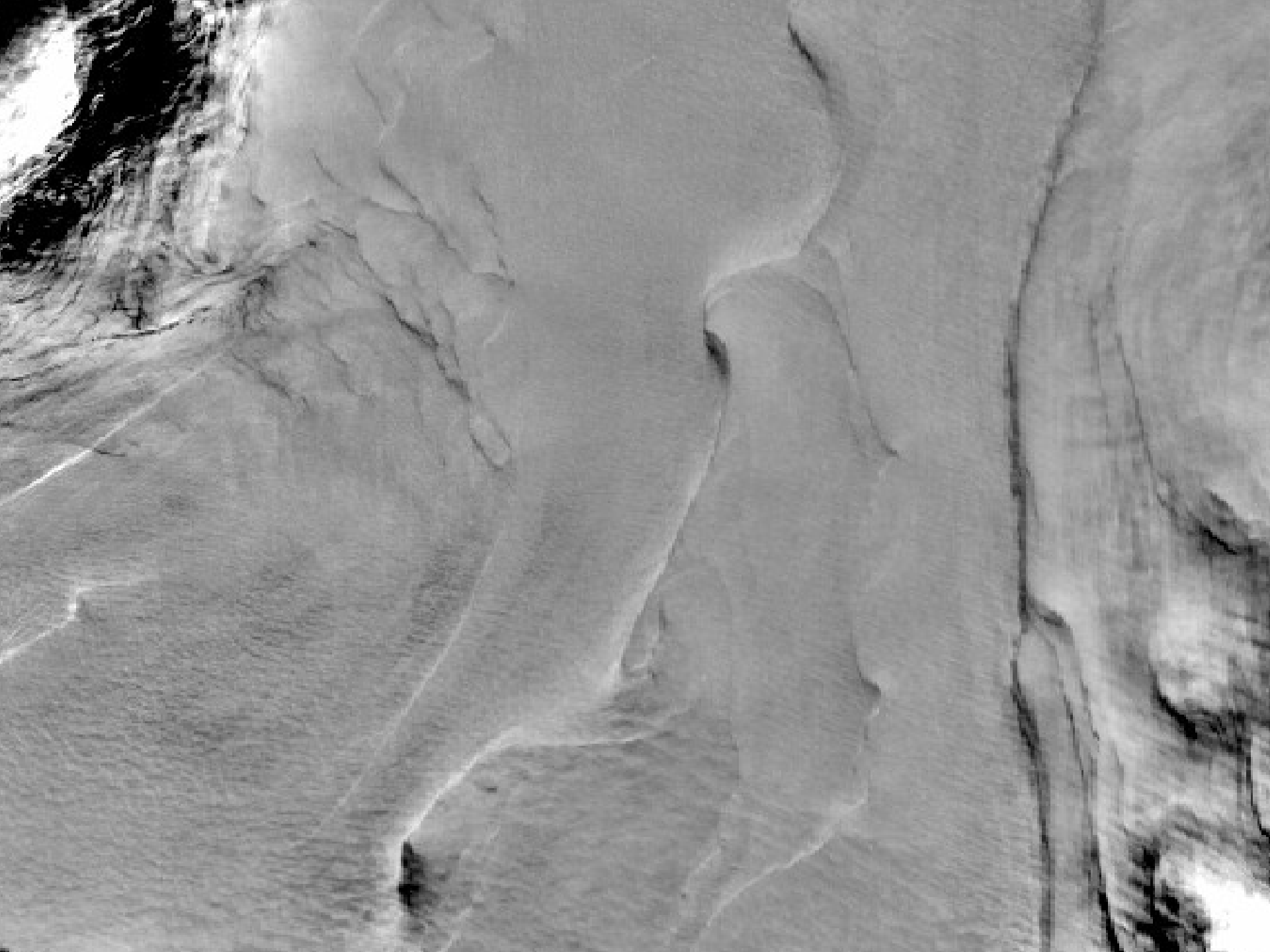
3-Day Weekly 100.0% datasets shown (4/4) MYD02QKM.A2010091.1805 from SST MODIS denoised (NASA, OceanDataLab)

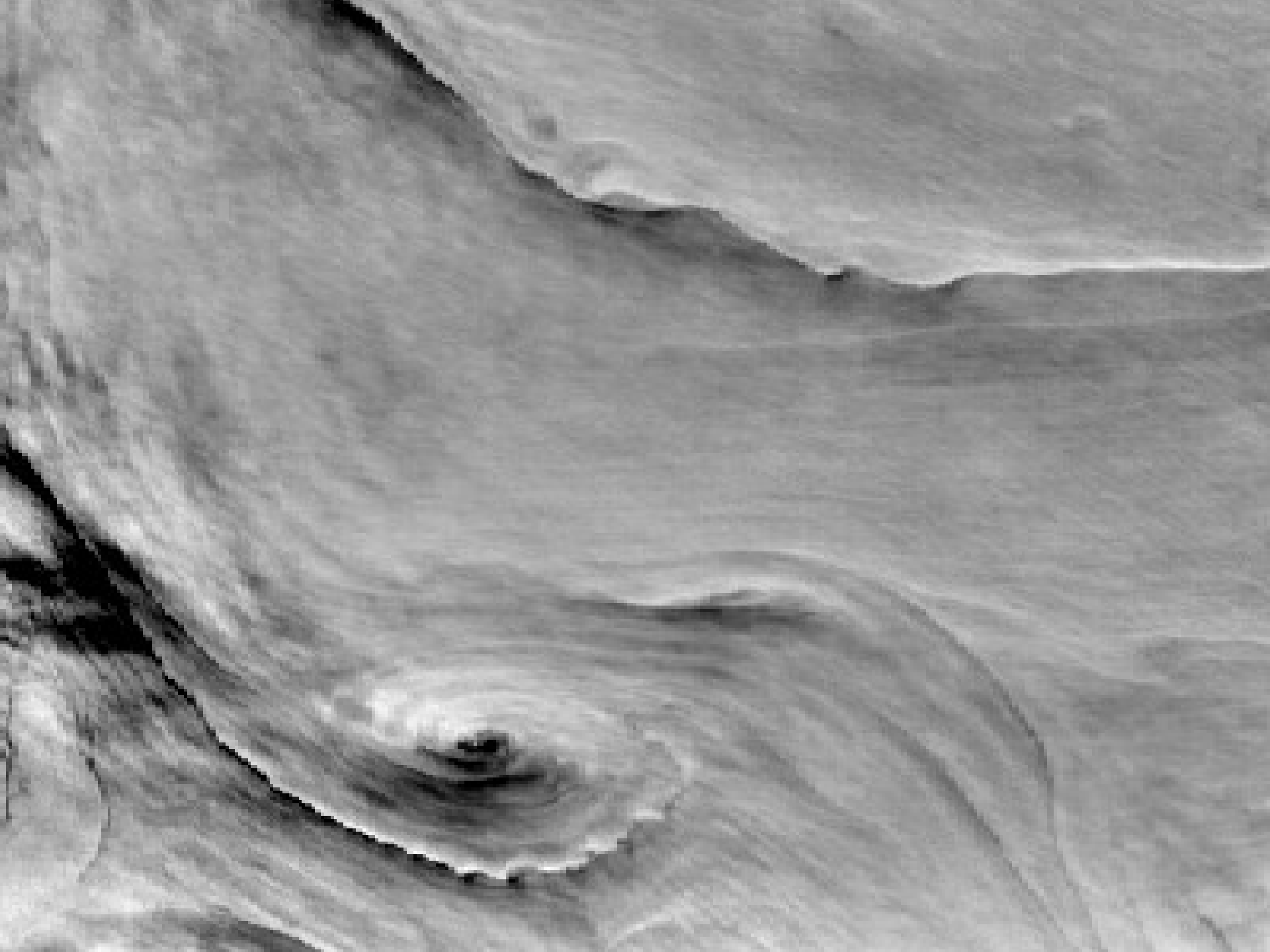




Meso- and submeso-scale details: the DrFab principle ?

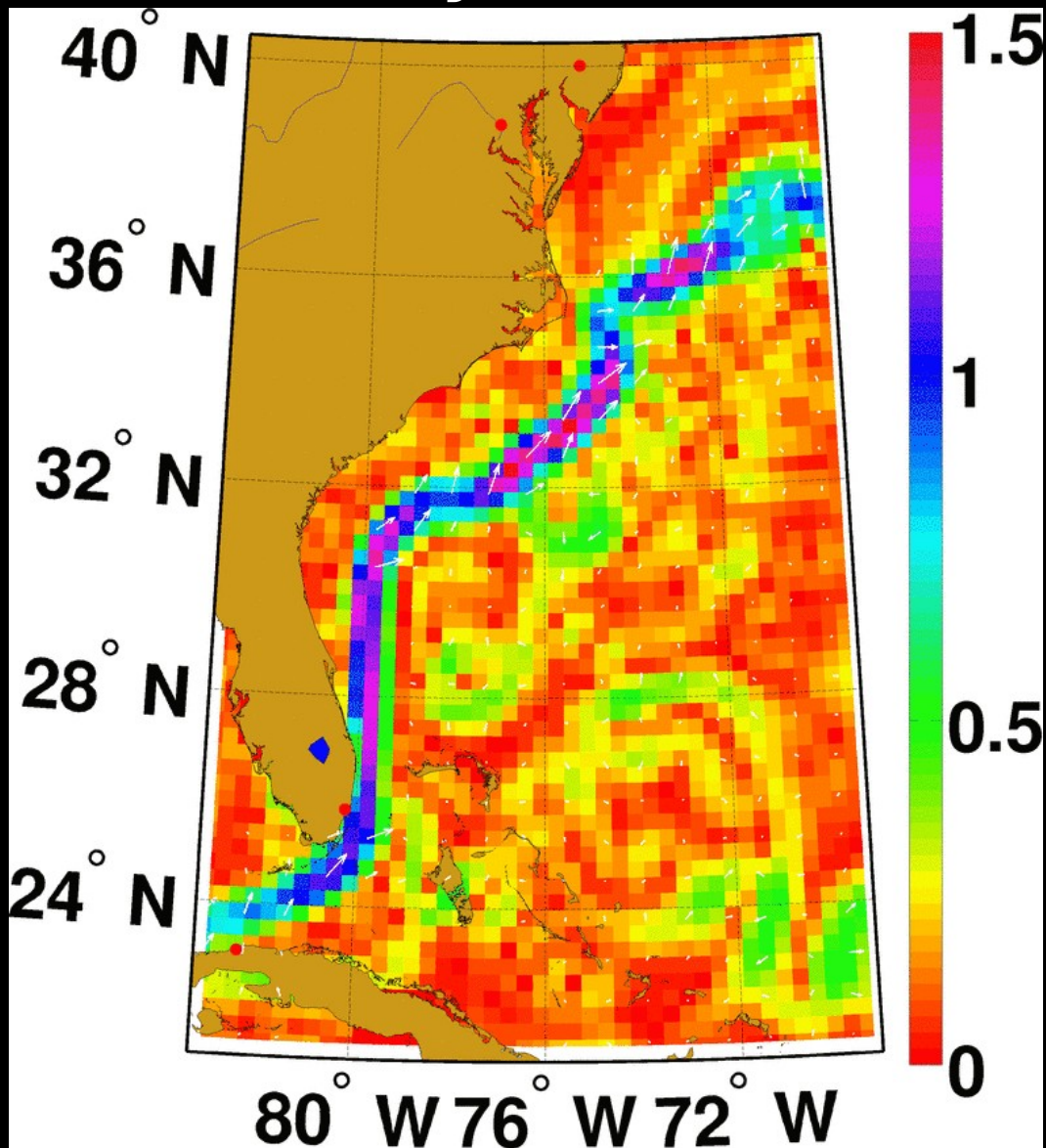






31Mar/07Apr (2010)

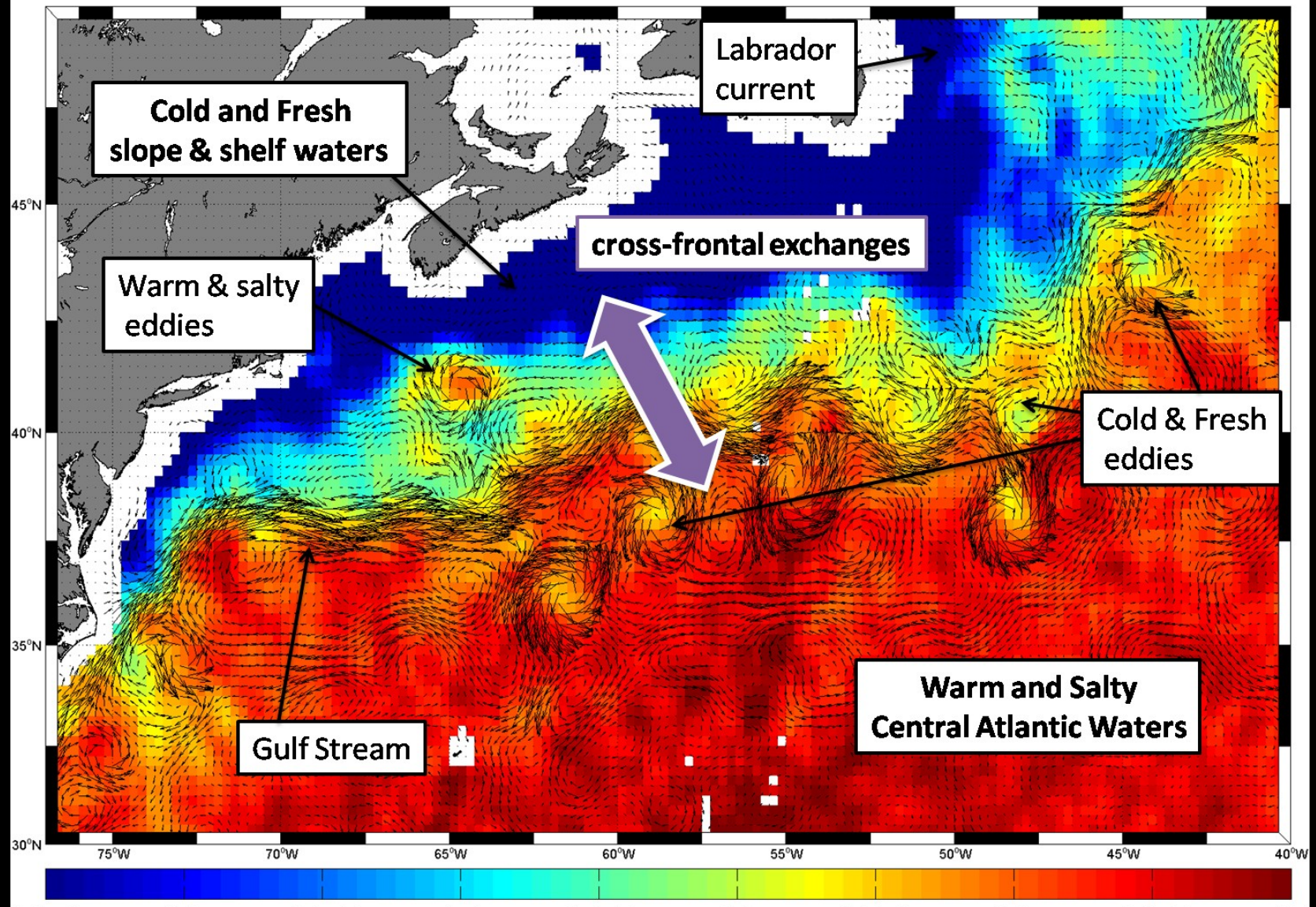
MODIS vs Altimetry-derived velocity field



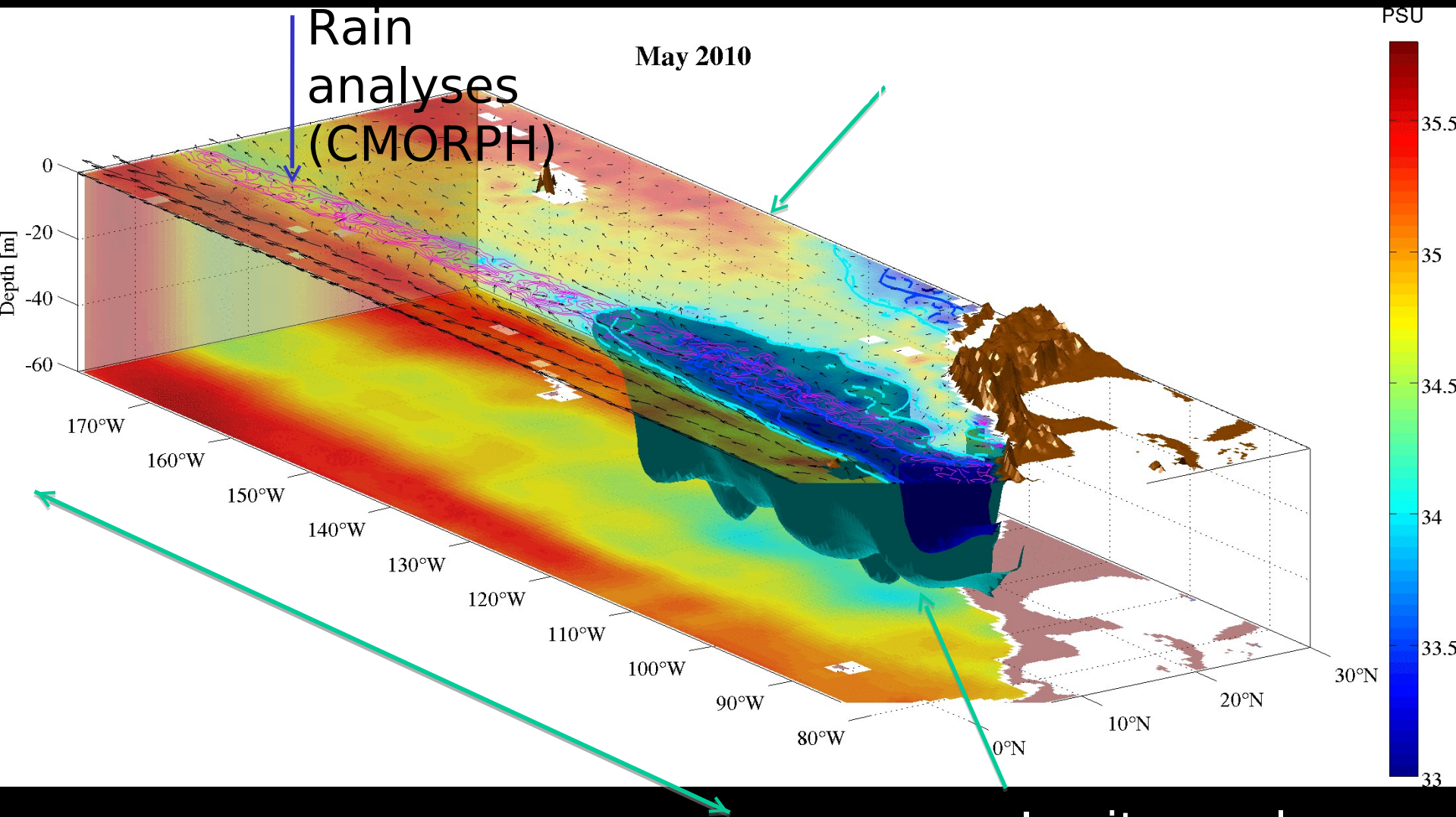




SMOS SSS (color)+ currents (vector) from 04/06 to 18/06 2012



Eastern Pacific Freshpool & 3D monitoring of the pool



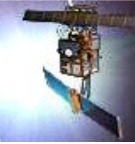
In situ analyses
(depth)

Application to Oil Spills Detection

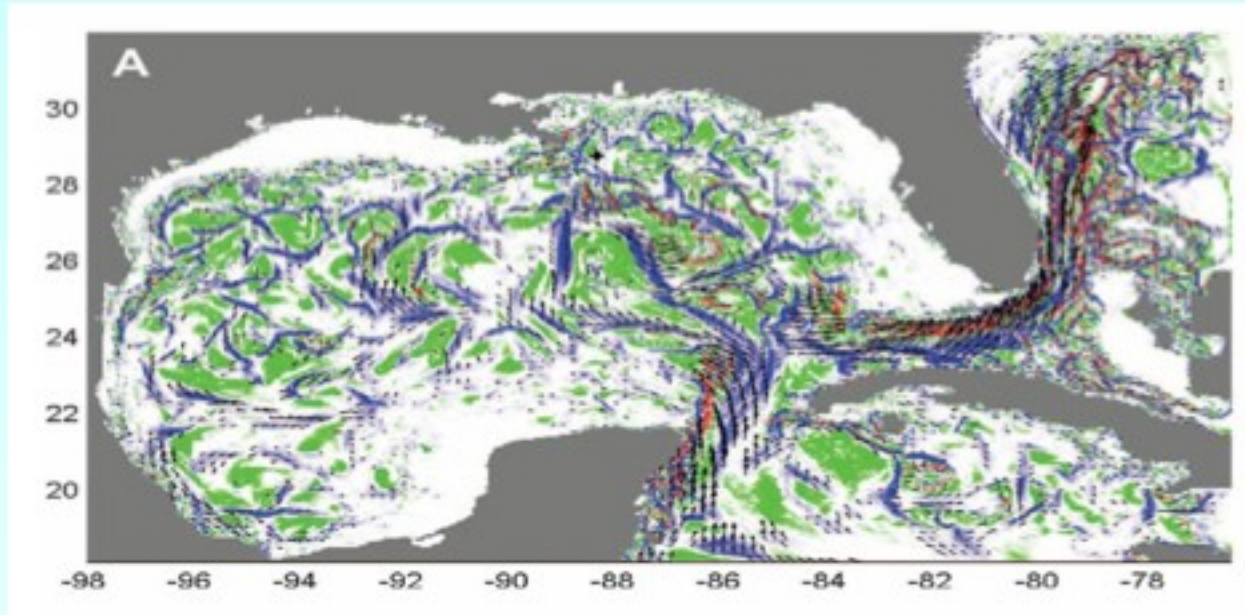


Deepwater Horizon
May 24, 2010
Terra/MODIS





The blended satellite products allow to estimate the impact of surface currents on the biogeochemical transport, on the dispersion of pollutants and oil spills

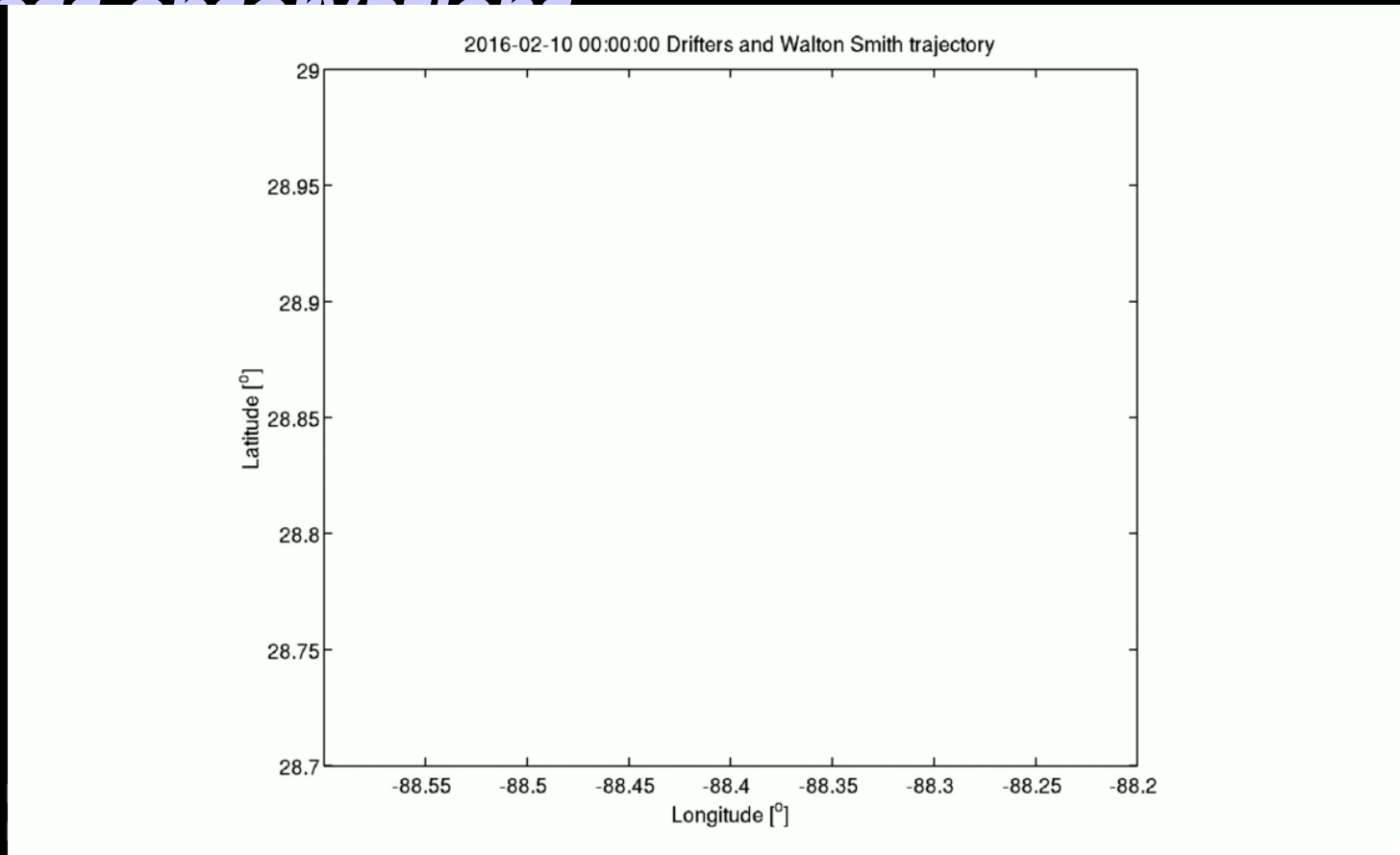


Forecast of oil spill dispersion in the Gulf of Mexico on 25 June 2010: red and blue show regions of strong oil dispersion within 3 days. This diagnosis, based on altimetric data, compared well with what was observed (Mezic et al, Science, 2010).

However these satellite datasets (altimetric and microwave data) cannot capture ocean dynamics at scales smaller than 100 km because of the resolution (or/and noise level).



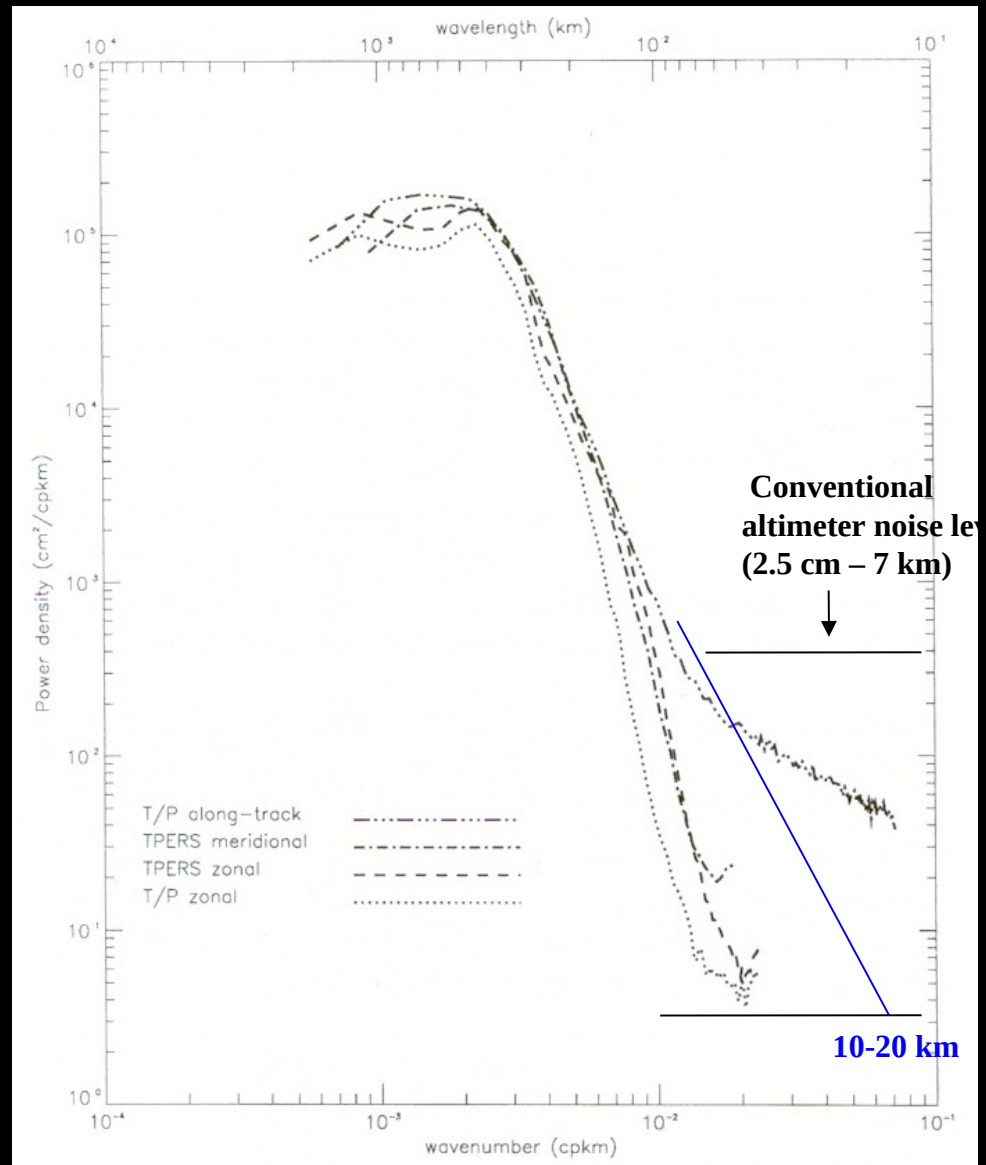
Intense deformation field at oceanic front inferred from directional sea surface roughness observations





High resolution altimetry mesoscale/submesoscale investigations

- **Should allow a characterization of submesoscale signals. Scales (wavelengths/2) between 10 and 100 km.**
- **Noise is a major issue (a goal of 1 cm / 1 km for an uncorrelated noise is quite challenging !).**
- **Time sampling will remain an issue for some applications.**





Total Surface current vs altimetric currents

Kinetic energy spectra yields in the Gulf Stream region.

(Callies & Ferrari, 2013)

Present nadir altimetry is smoothed at scales < 100 km along-track

Differences in total surface currents and altimetry derived geostrophic currents are expected between 20-100 km => to explore with SWOT & total surface current obs

Gulf Stream : An interior QG-turbulence regime exists at large scales and an internal-wave regime at small scales, with the transition occurring at about 20 km.

Enhanced submesoscale energy may occur in the presence of a deep winter mixed layer

How does this vary, regionally, seasonally?

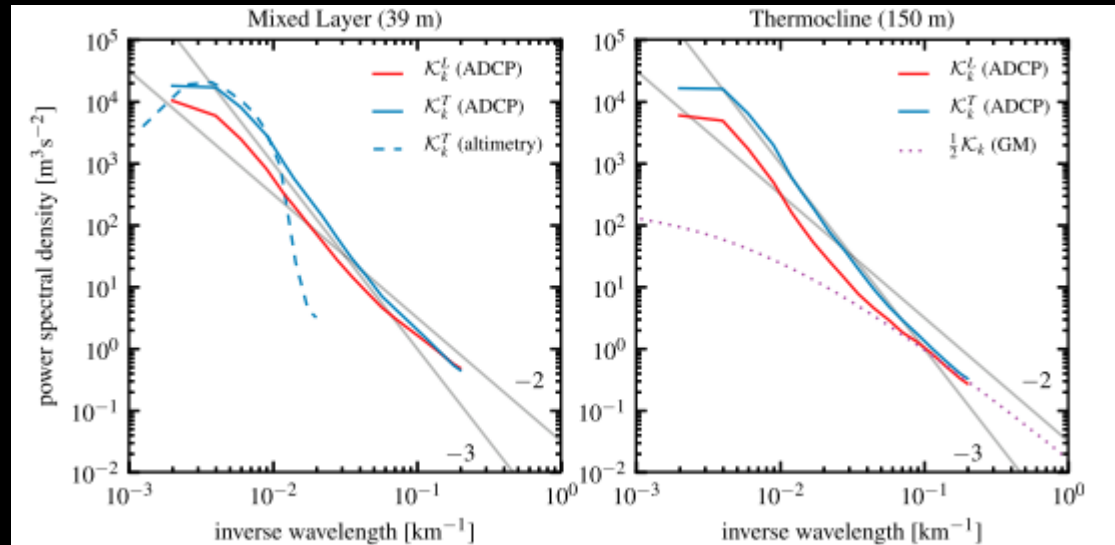


FIG. 5. Gulf Stream region wavenumber spectra of longitudinal and transverse kinetic energies \mathcal{K}_k^L and \mathcal{K}_k^T in the (left) mixed layer (39-m depth) and (right) thermocline (150-m depth) from in situ observations (ADCP). The wavenumber spectrum of surface transverse kinetic energy \mathcal{K}_k^T from altimetry (left) and the GM model spectrum for kinetic energy \mathcal{K}_k in the thermocline (right) are also shown. In both panels, lines with slopes -2 and -3 are given for reference (gray solid lines). Confidence intervals are too small to be visible.



APRIL 2010

NOTES AND CORRESPONDENCE

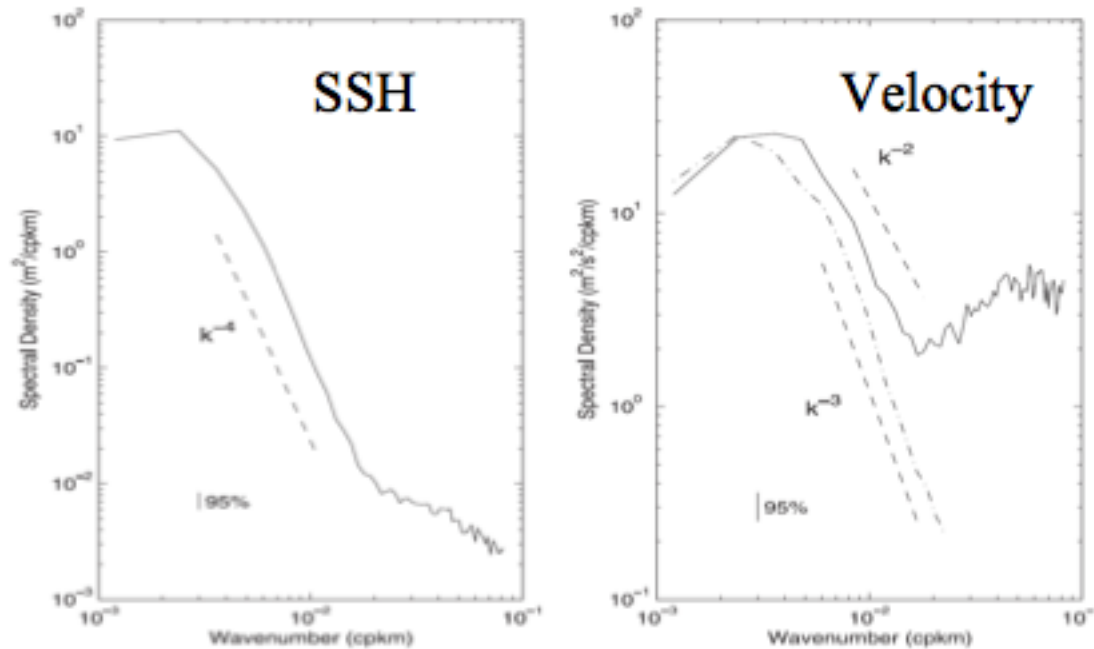


FIG. 3. (left) SSH and (right) geostrophic velocity spectra from altimetry measurements, superimposed with kinetic energy spectrum (dashed-dotted) from *Oleander* observations. Dashed lines indicate slopes of -4 , -3 , and -2 , respectively. The 95% confidence interval is marked.

Wang et al., JPO 2010

Velocity spectrum: k^{-3} from ADCP data (*Oleander* dataset) **steeper than k^{-2}** from SSH

Kinetic energy: **smaller energy** level with ADCP data than altimetric data

Temperature spectrum: $k^{-2.3}$ (closer to velocity spectrum from SSH)



We hypothesize that **vertical mixing** within the ML explains the departure of surface currents from geostrophy

$$-f \mathbf{k} \times \mathbf{u}_{ml} - \frac{\partial}{\partial z} A_v \frac{\partial \mathbf{u}_{ml}}{\partial z} = -\frac{1}{\rho_o} \nabla p$$

Coriolis term

Wind-forced mixing

Pressure (ssh) gradients forced by eddy turbulence

After integration over the mixed-layer depth (using the SQG approximation for p), we get :

$$\widehat{\mathbf{u}}_e(k_x, k_y) = \widehat{\mathbf{u}}_g(k_x, k_y, 0) \frac{f}{kNH} [1 - \exp(-\frac{kNH}{f})]$$

Surface currents

Geostrophic currents (from SSH)

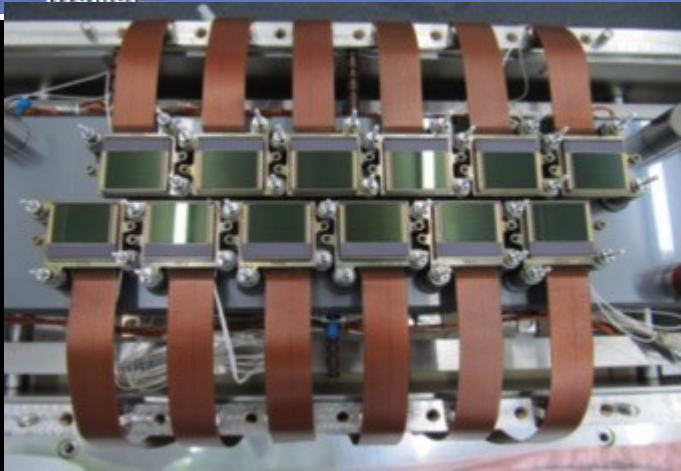
Wind-forced ML depth



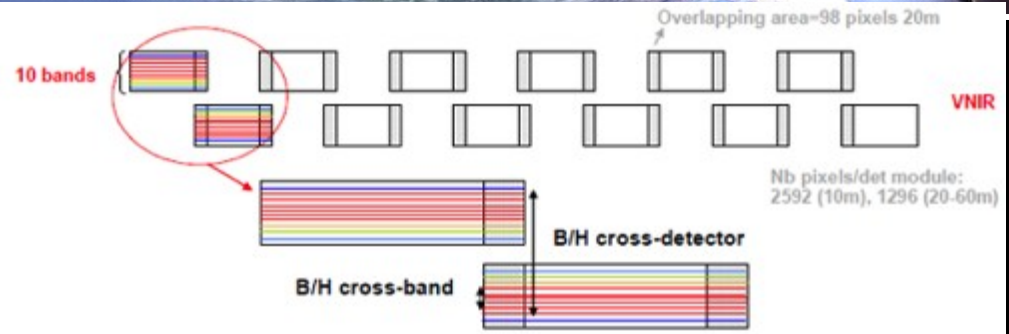
Discovering Ocean Dynamics from Space: several strategies

- Numerous Remote sensing measurements to invite feature tracking techniques (e.g. MCC, optical-flow methods)
 - Very high resolution (100 m – 1 km) SST, Ocean Colour, radar and optical roughness images
 - Low resolution Altimetry (80 km)
 - Mesoscale Ocean Wind Vector Scatterometry and Microwave SST and SSS (25 km)
- Increased In Situ measurements
 - Fixed networks, ARGO floats, drifters, ship tracking
- Dynamical frameworks
 - Operational models, Quasi-geostrophy, Surface Quasi-geostrophy
 - Ekman, wave-induced Stokes drift
 - Swell system anomalous propagations

Sentinel-2 MSI Features = New Opportunities to image ocean surface waves and dispersion properties



Sentinel-2 detectors

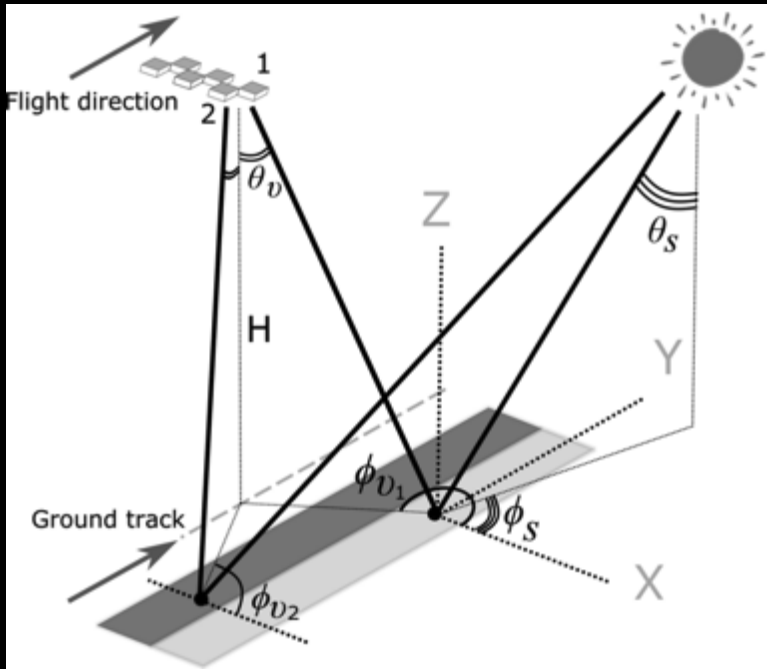


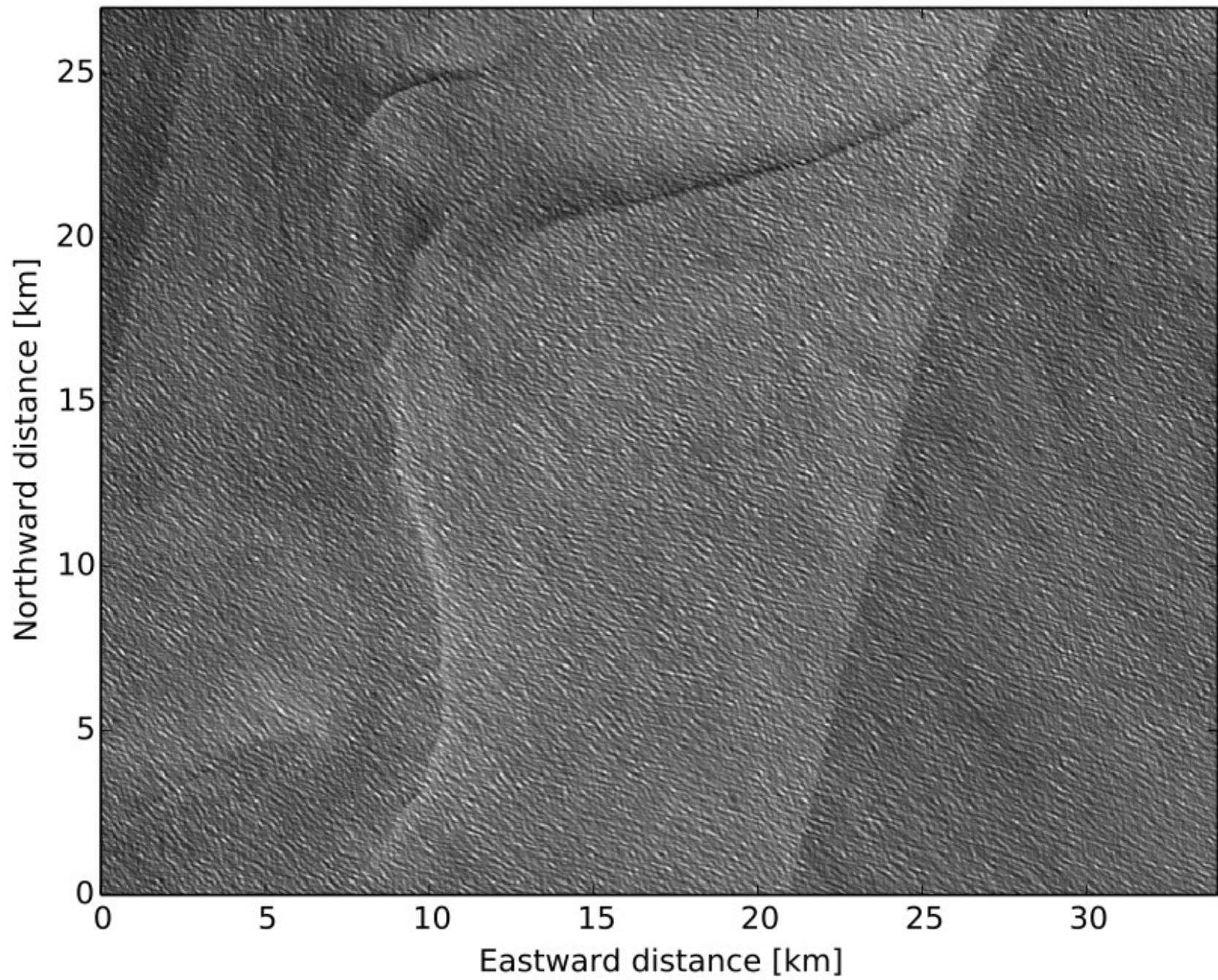
12 clusters (detectors), 13 lines of sensors (bands) in each

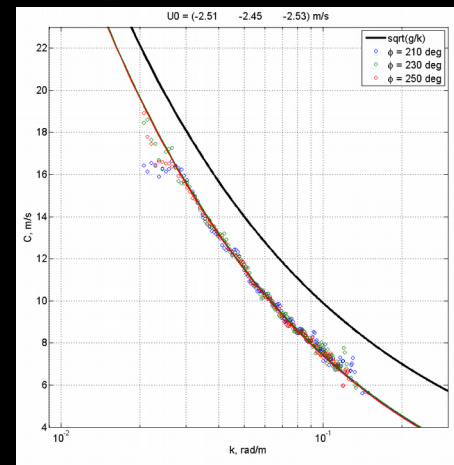
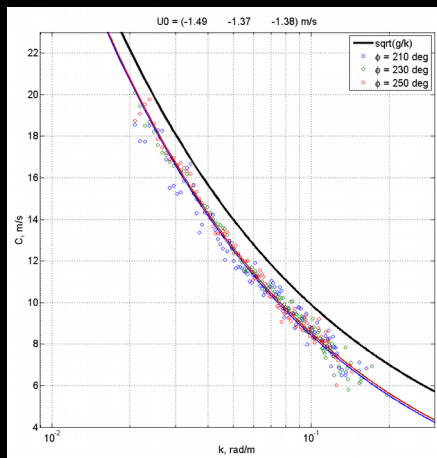
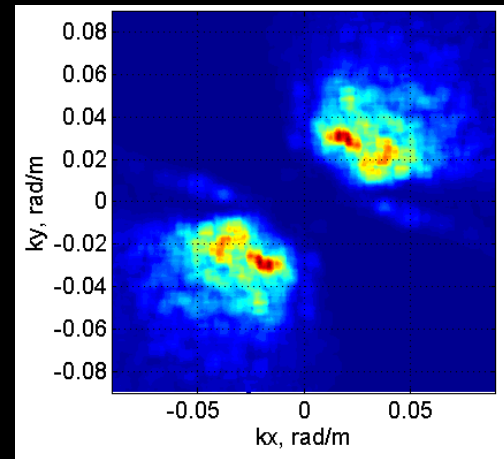
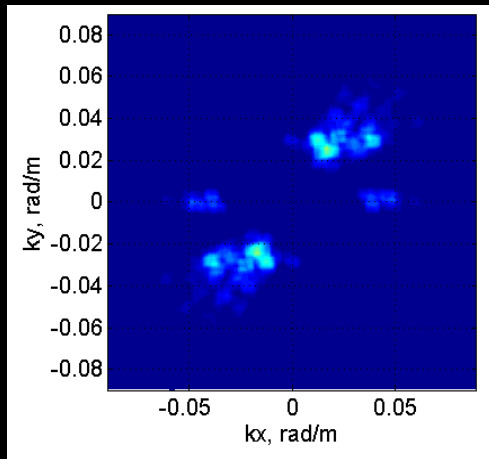
Odd clusters are looking forward, even clusters are looking backward, spectral channel sensors also have relative displacement

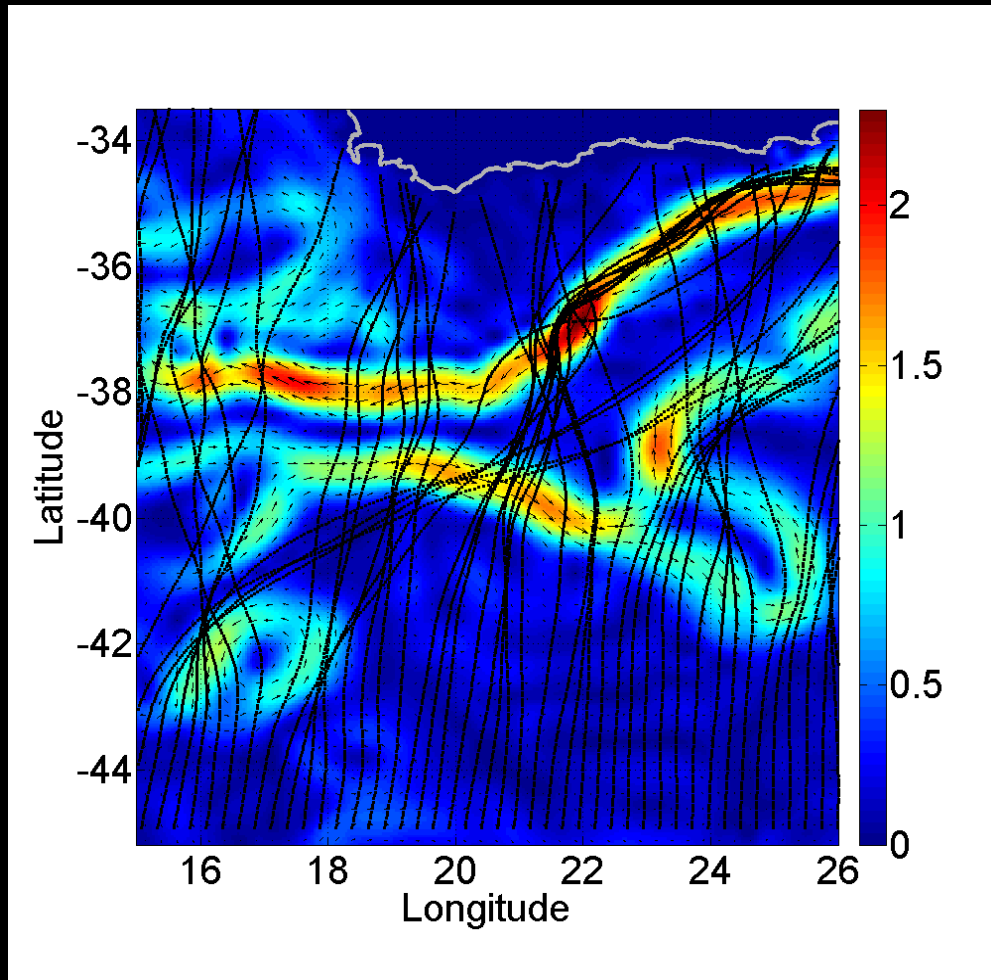
Parallax angle between the two alternating odd and even clusters of detectors results in a shift along track of approximately 46 km (maximum).

Inter-band measurement parallax amounts to a maximum along track displacement of approximately 14 km.









Wave-rays of an incoming 75 degree (counter clockwise from the East) 250 m swell at -45 degree latitude,

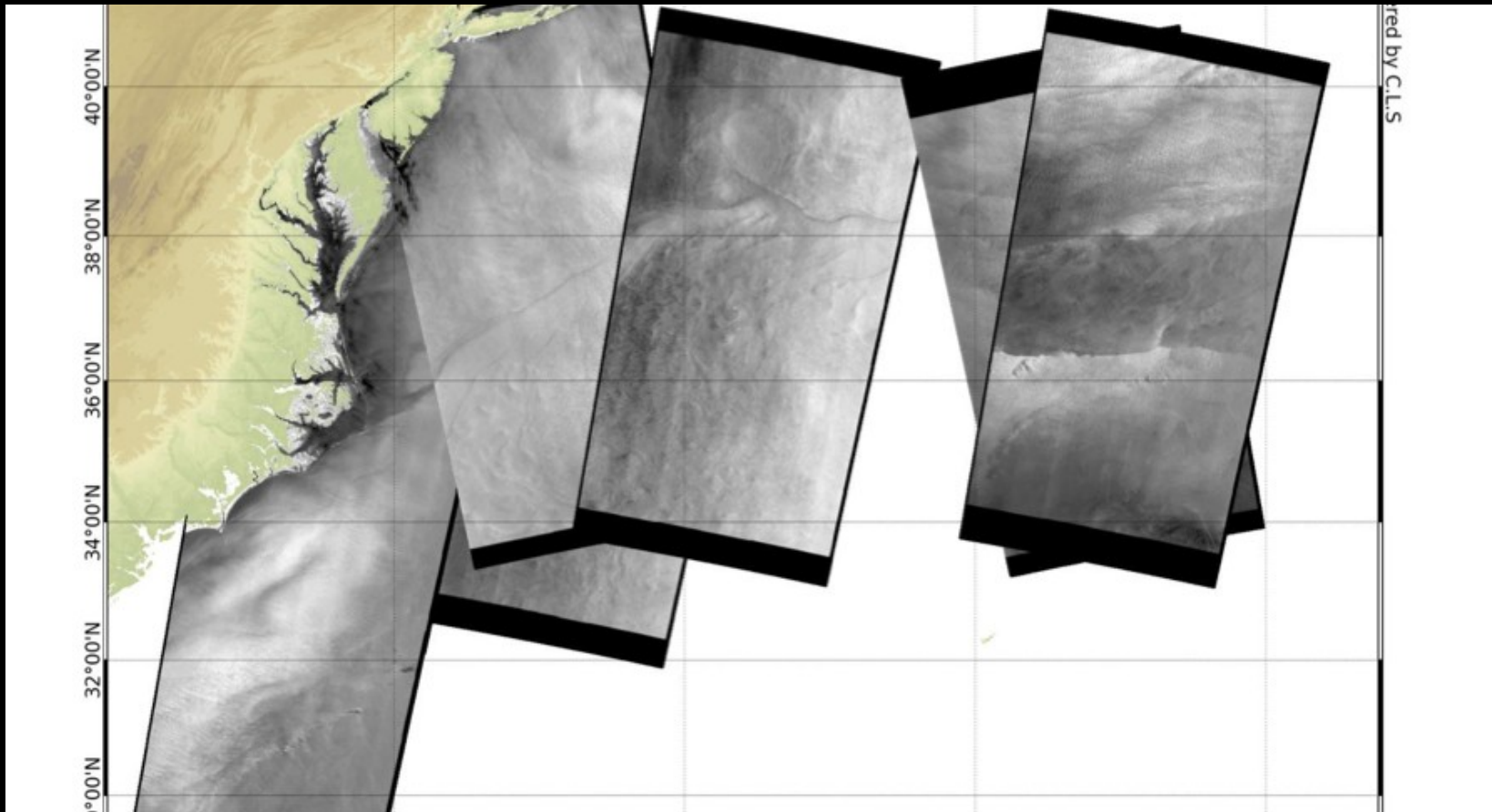


Gulf Stream roughness changes

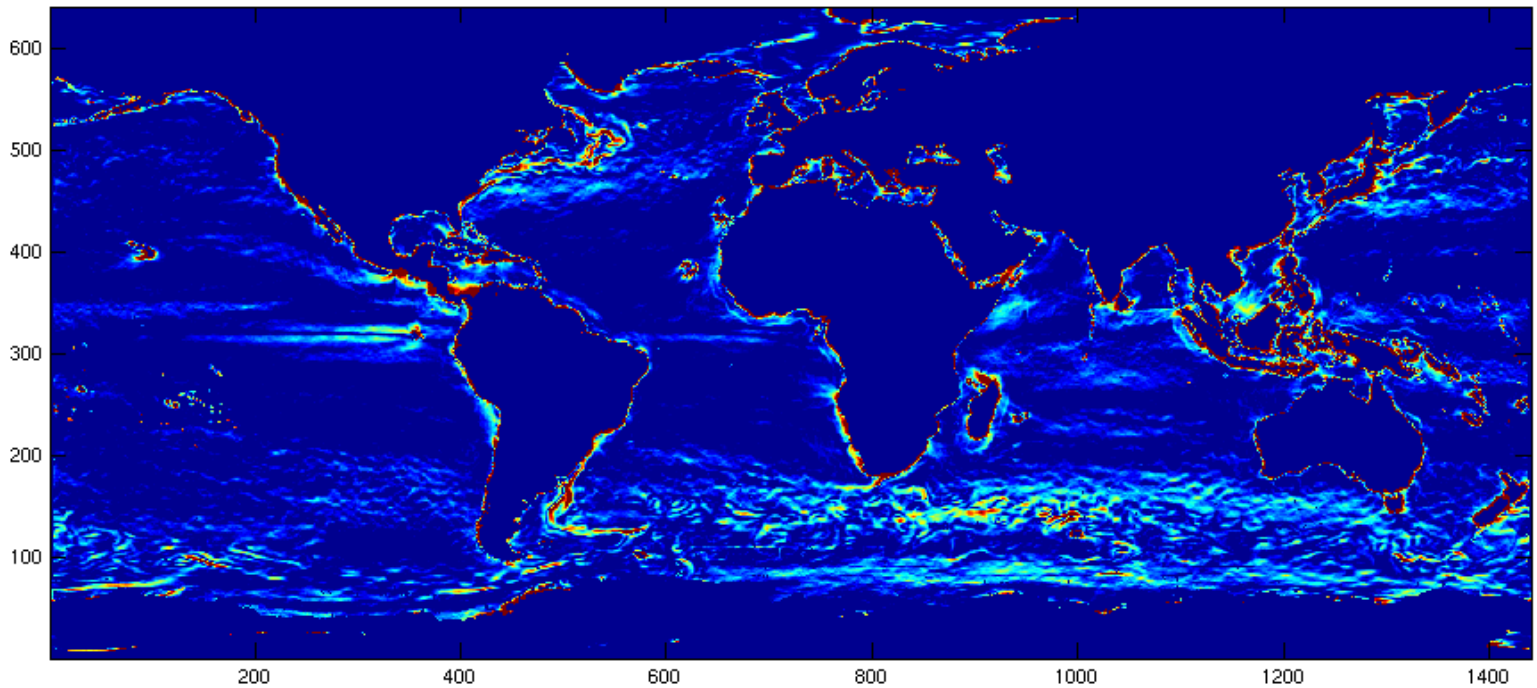




Gulf Stream roughness changes

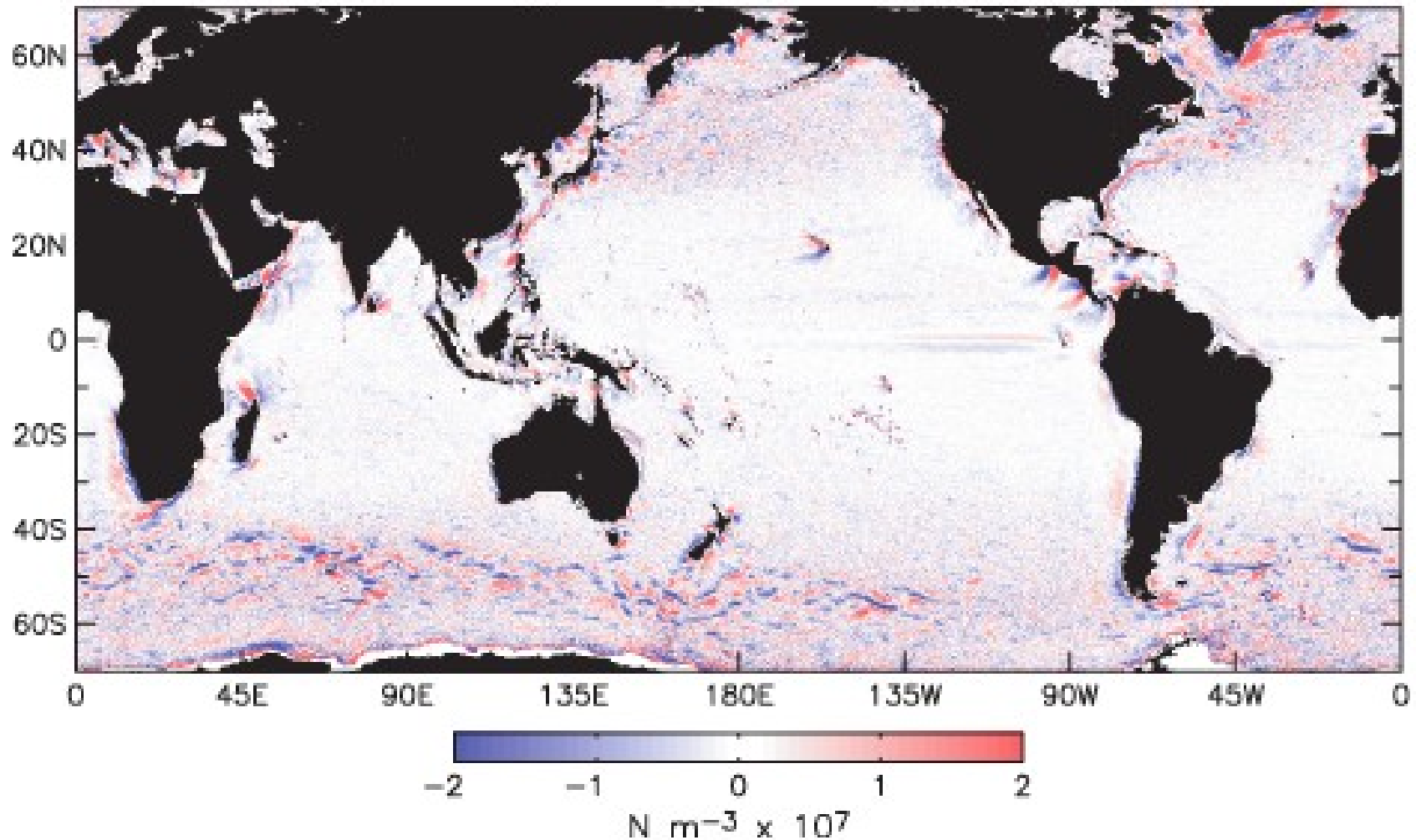


Meso-scale Air-Sea Interactions (High-pass filtered surface wind speed)



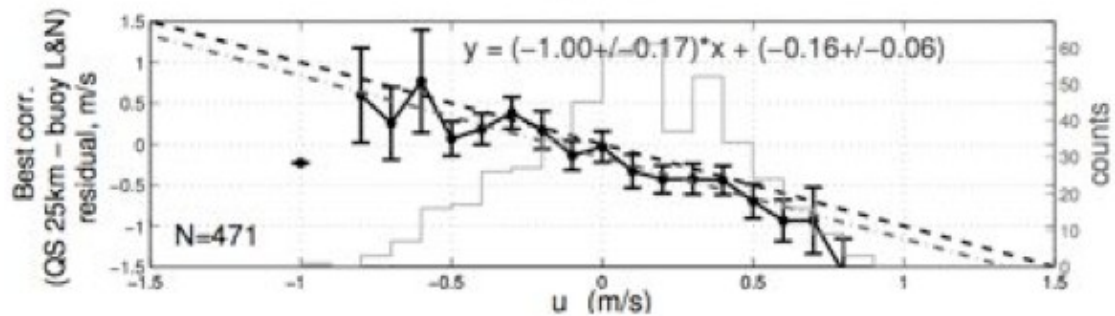
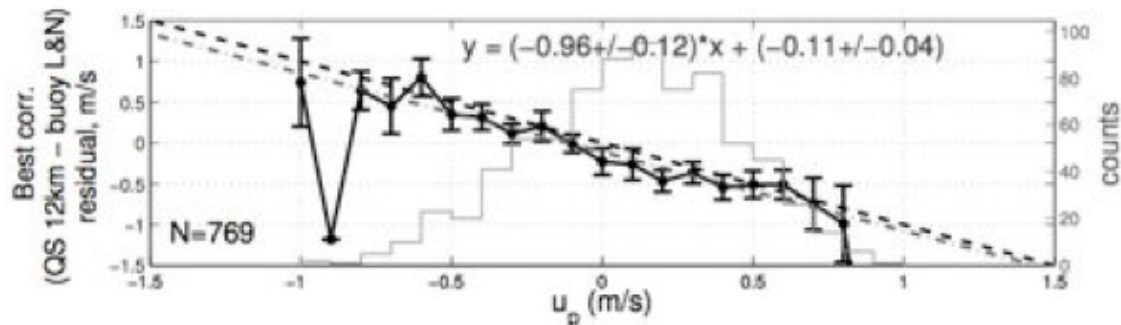
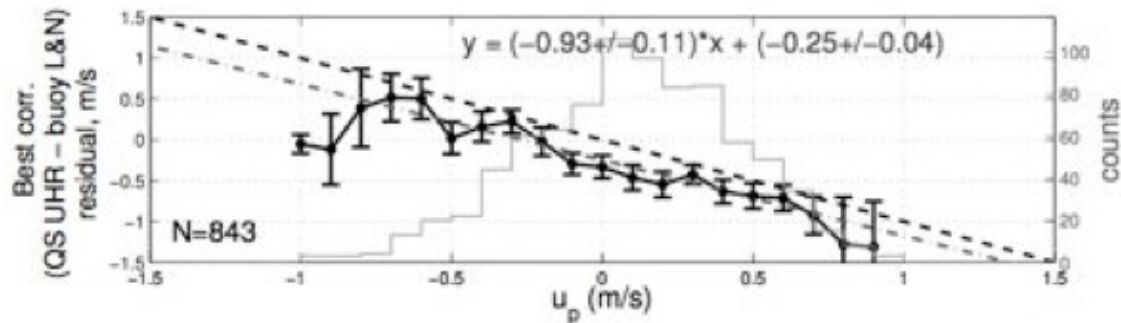
Meso-scale Air-Sea Interactions
Mean scatterometer wind-product curl (Chelton et al., 2007)

Spatial High-Pass Filtered Wind Stress Curl



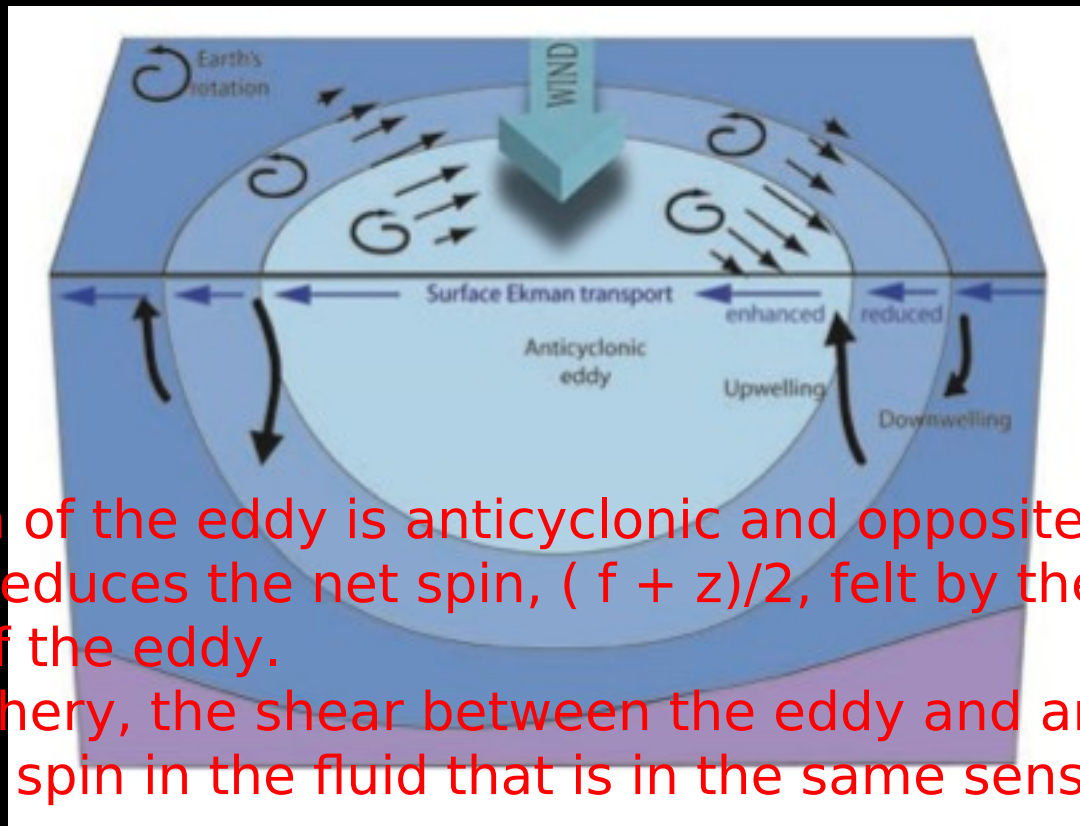


$$u_p = |u| * \cos(\phi_{\text{buoycurr}} - \phi_{\text{buoywind}})$$





Coupled Ocean-Atmosphere system: Eddy/wind interactions , i.e. the nonlinear Ekman effects



The rotation of the eddy is anticyclonic and opposite to Earth's rotation. It reduces the net spin, $(f + z)/2$, felt by the fluid toward the inside of the eddy.

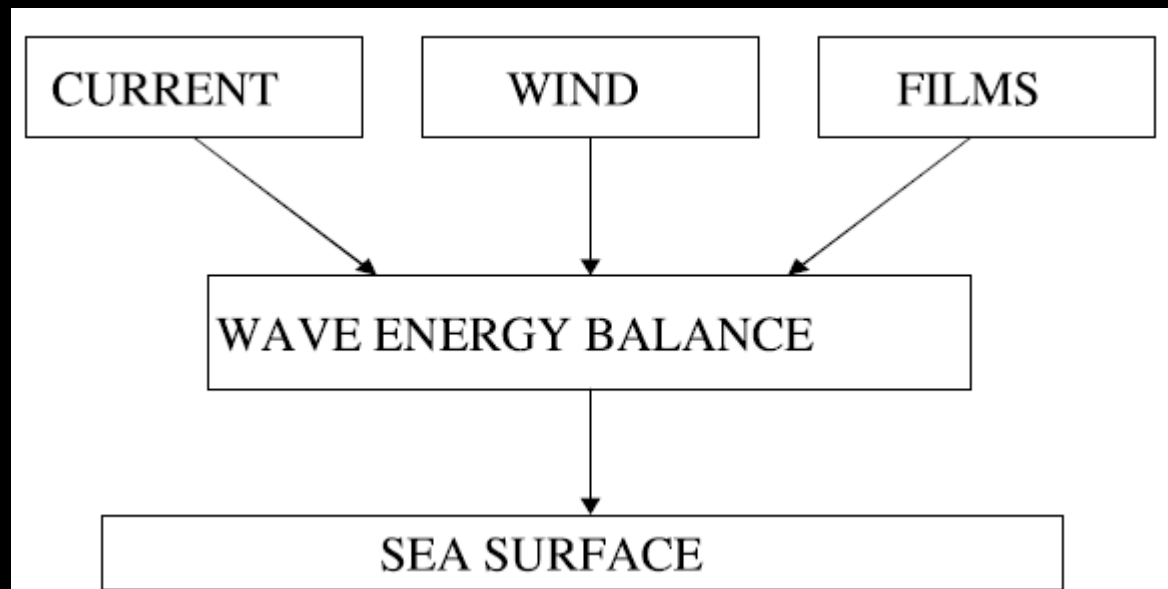
At the periphery, the shear between the eddy and ambient fluid generates a spin in the fluid that is in the same sense as Earth's rotation

The divergence/convergence of the Ekman transport can then drive alternate up/down motions

Sea Surface Roughness (SSR) dynamical variations

$$\frac{\partial N(\mathbf{k})}{\partial t} + (c_{gi} + u_i) \frac{\partial N(\mathbf{k})}{\partial x_i} - k_j \frac{\partial u_j}{\partial x_i} \frac{\partial N(\mathbf{k})}{\partial k_i} = Q(\mathbf{k})/\omega$$

$$Q(\mathbf{k}) = \beta_\nu(\mathbf{k})\omega E(\mathbf{k}) - D(\mathbf{k}) - Q^{nl}(\mathbf{k}) + Q^{wb}(\mathbf{k})$$



$$\begin{aligned} & \frac{\partial \tilde{N}(\mathbf{k})}{\partial t} + c_{gi} \frac{\partial \tilde{N}(\mathbf{k})}{\partial x_i} \\ & = \omega^2 k^{-5} [\omega^{-1} m_k^{ij} u_{i,j} B_0 - \tilde{B}/\tau + \tilde{\beta} B_0 + \tilde{I}_{sw}] \end{aligned}$$

$$m_k^{ij} = k_j \partial \ln \tilde{N}_0 / \partial k_i$$

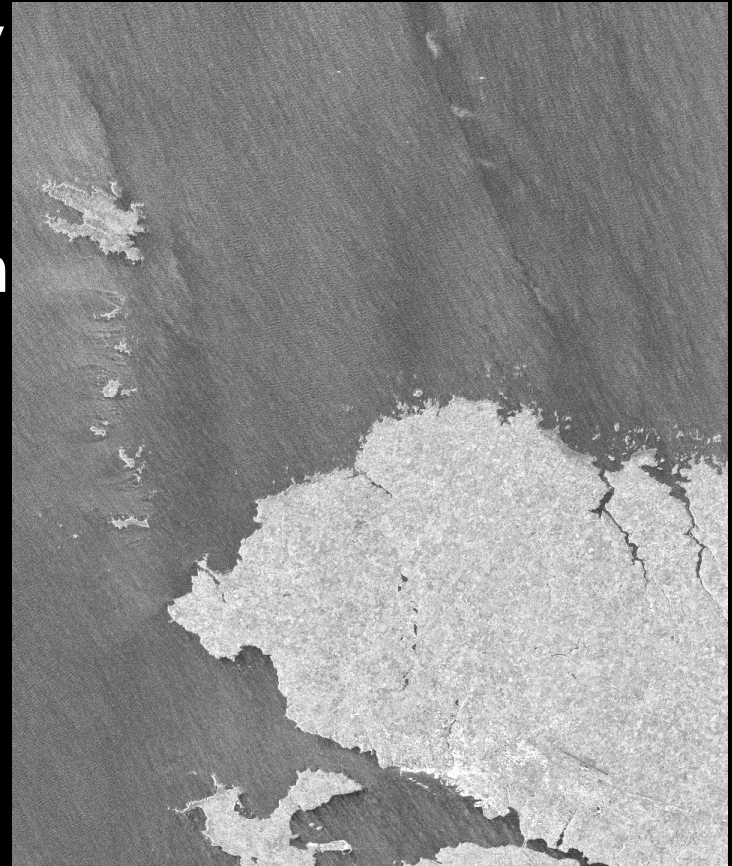


Direct ocean surface Doppler velocities from space

SRTM 2-Antenna Interferometry

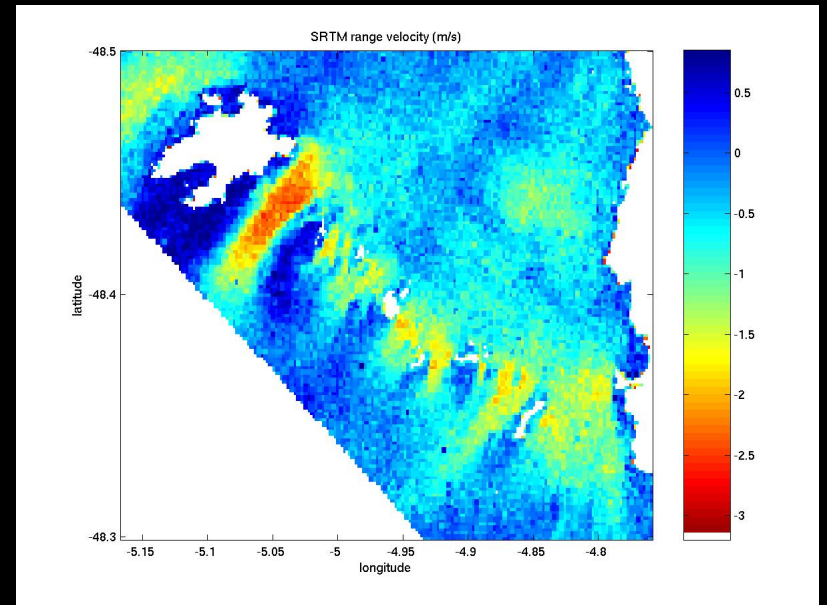
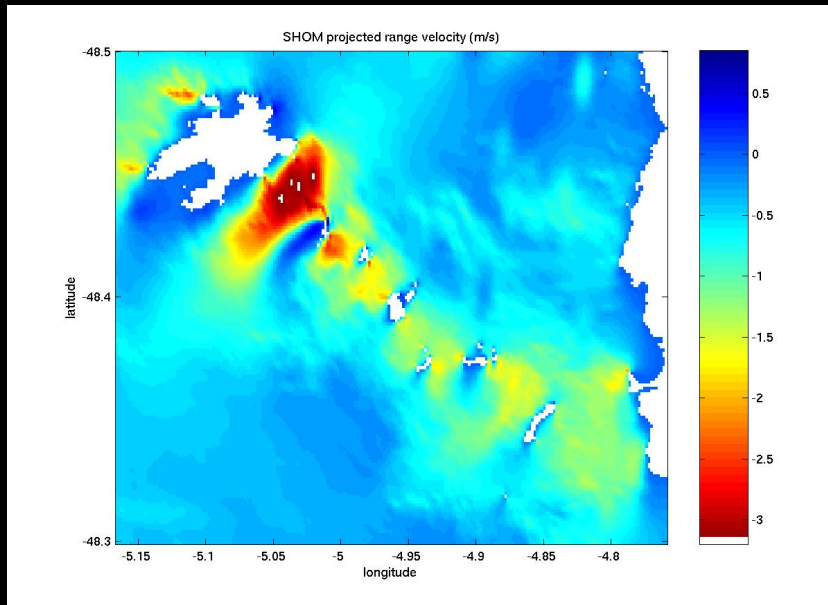
Ultra-high resolution

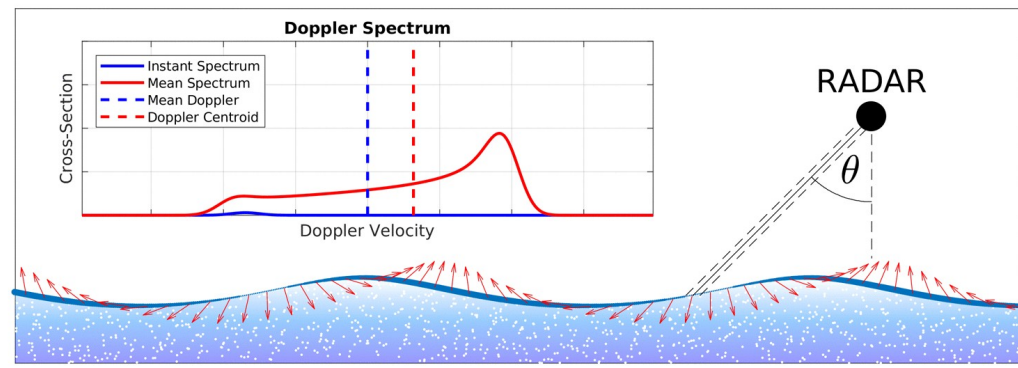
Limited to line-of-sight direction





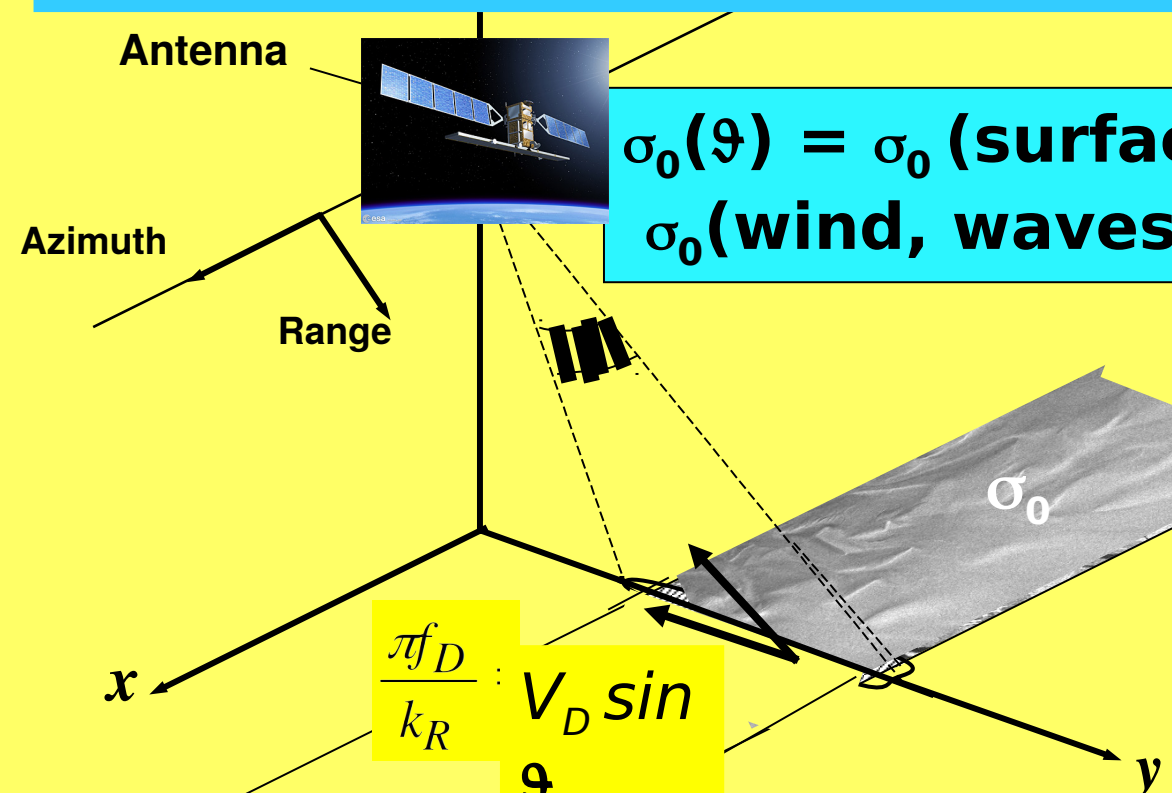
To obtain direct ocean surface velocities from space





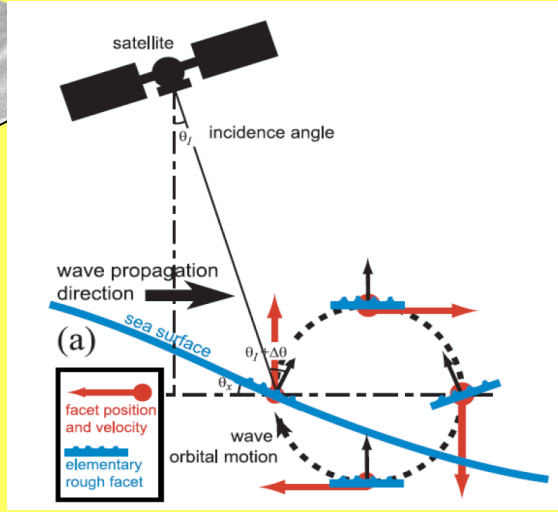


APPROACH: Combined Roughness and Doppler Shift



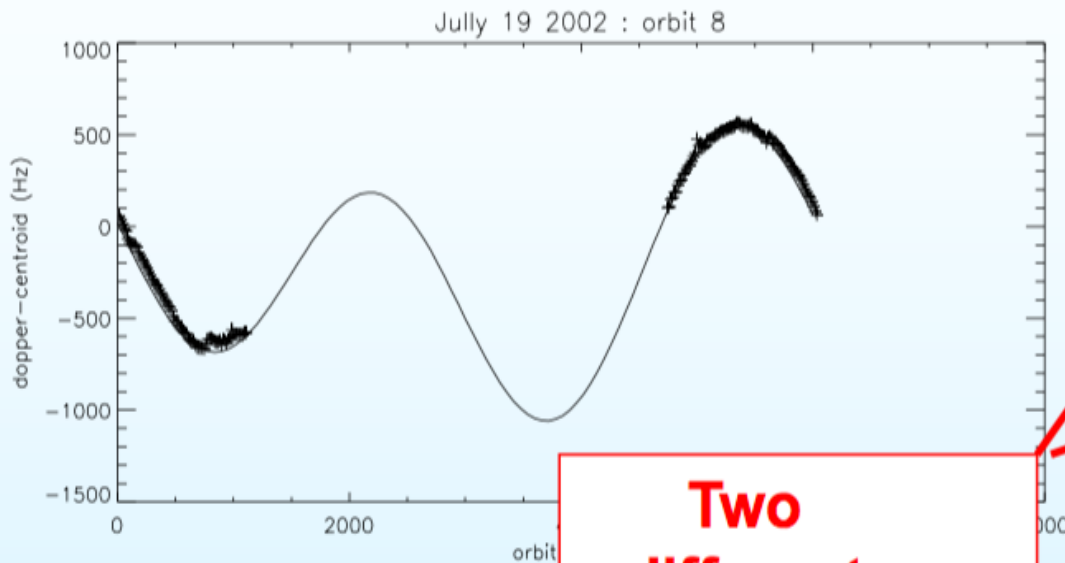
$$\sigma_0(\vartheta) = \sigma_0 \text{ (surface roughness)} = \sigma_0 \text{ (wind, waves, breaking, current)}$$

$$\mathbf{V}_D = \mathbf{V}_D \text{ (wind driven scatterer, waves, breaking, current)}$$

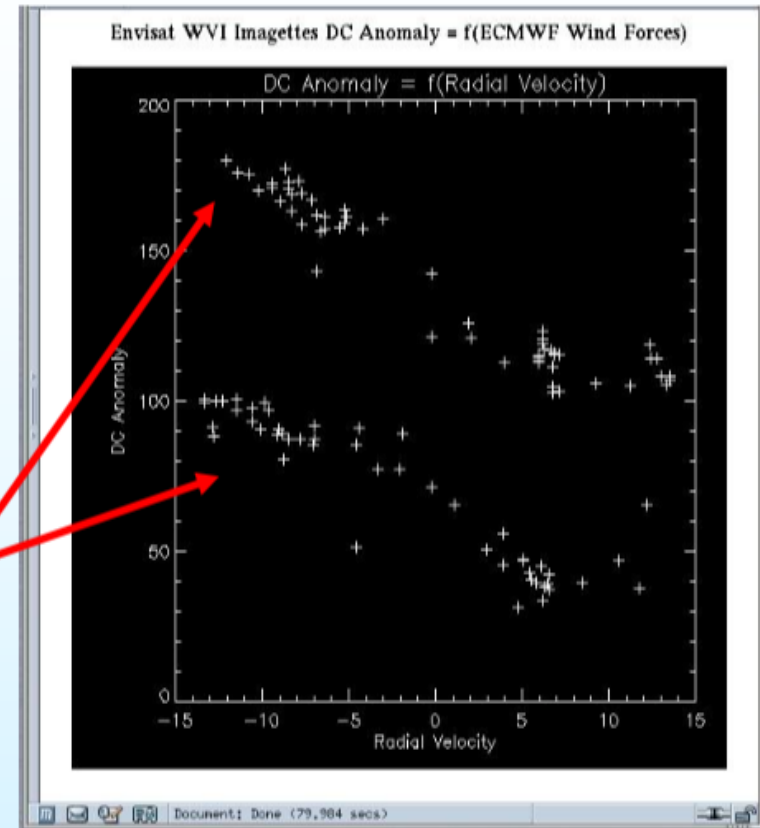


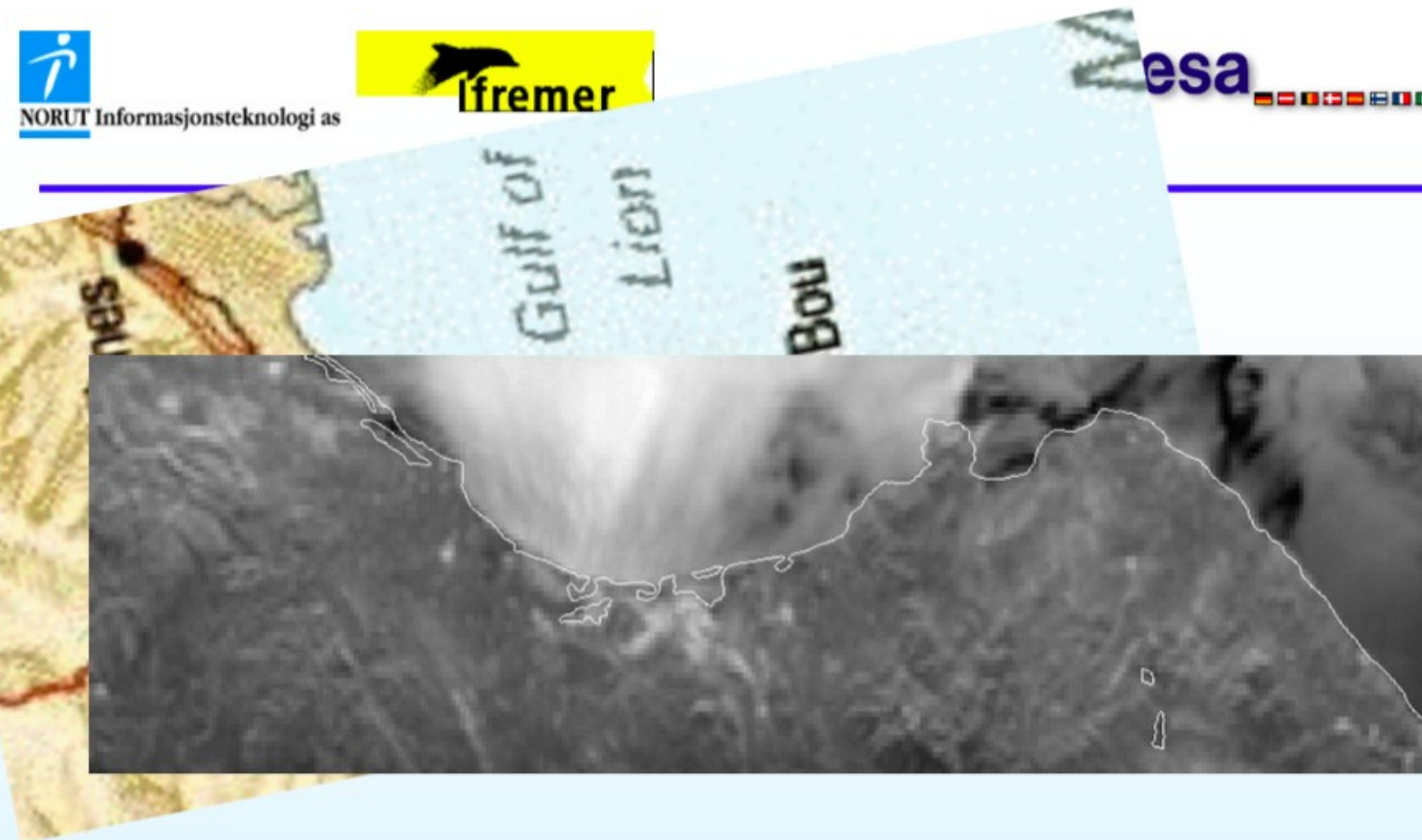


doppler centroid anomaly



**Two
different
tracks**

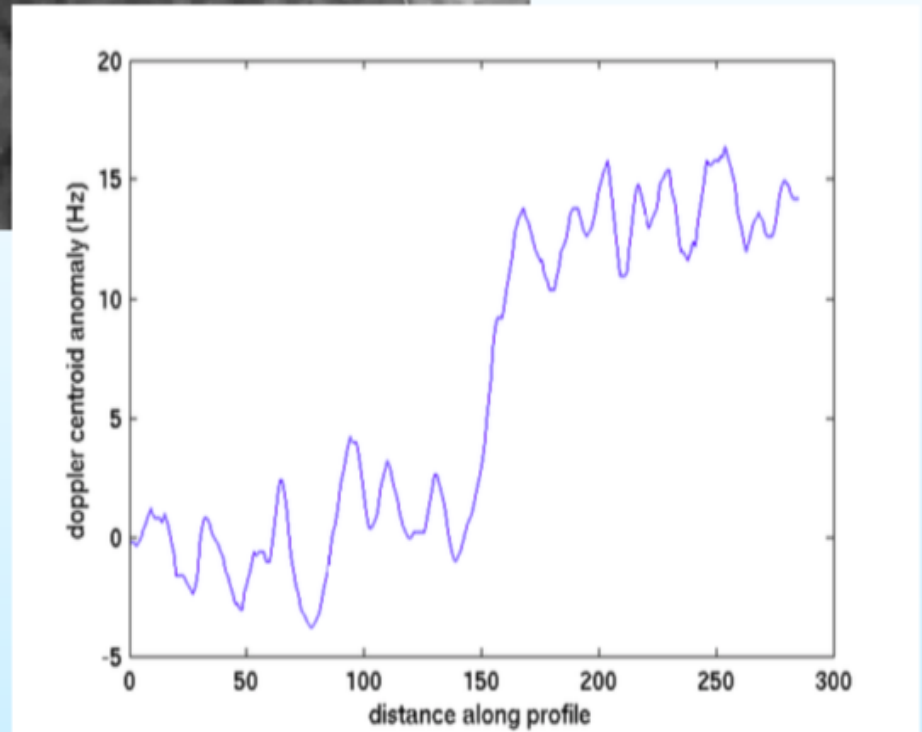
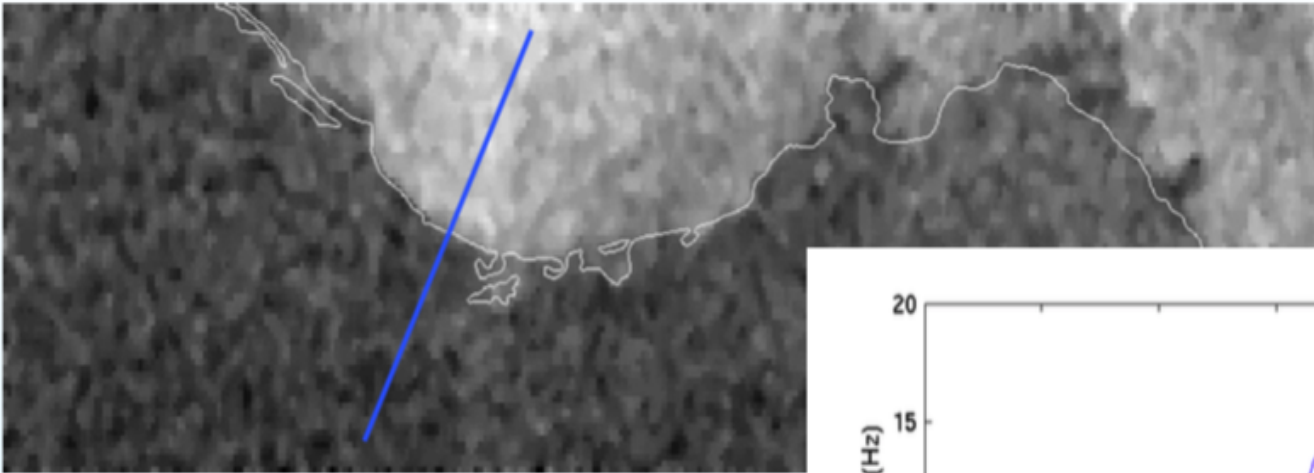




**Comparison with a similar ERS 2 SLC image
doppler centroid analysis**

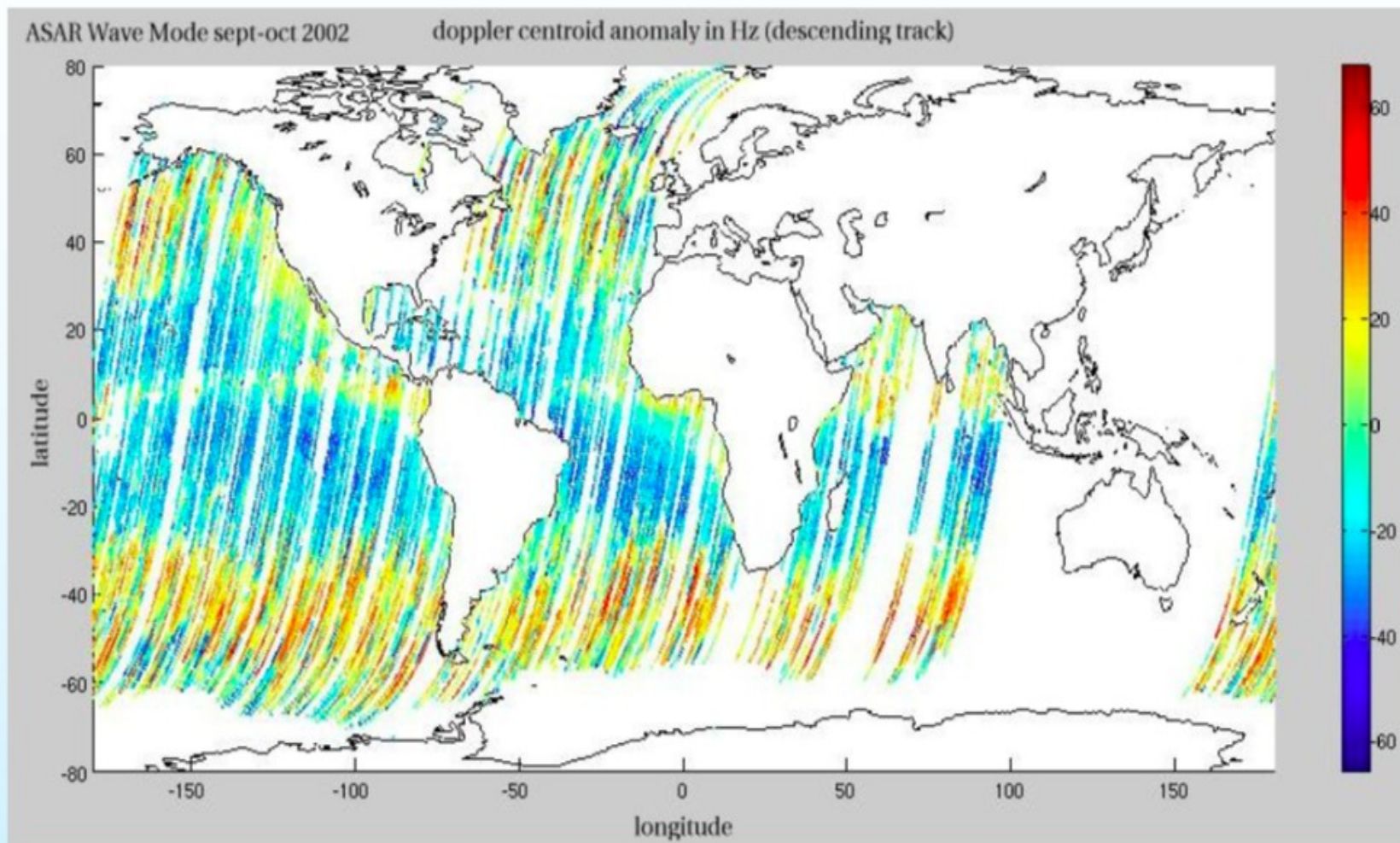


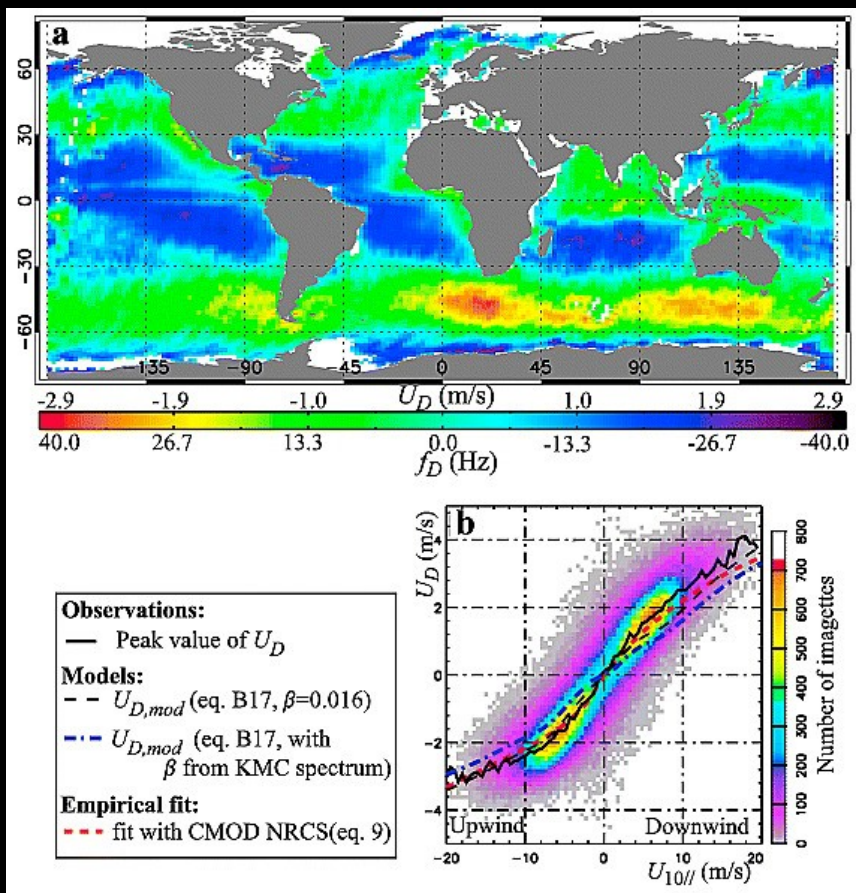
Doppler anomaly chart





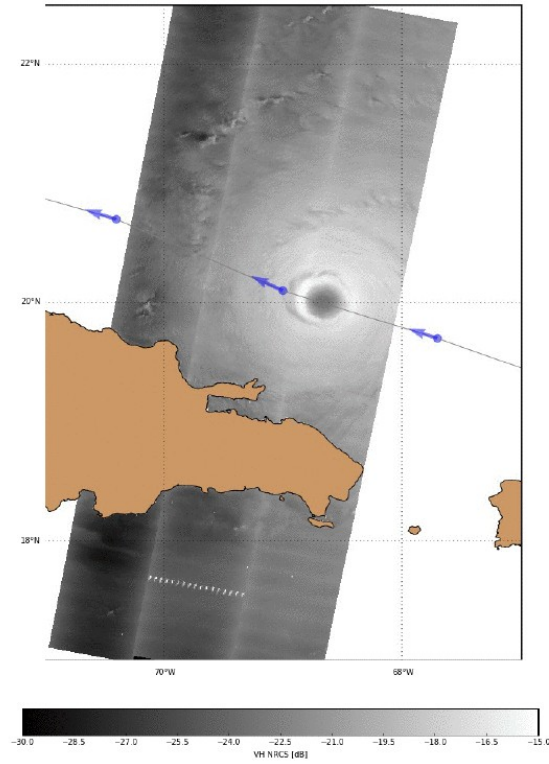
Doppler centroid anomaly on Wave mode level1b (descending tracks)







#IrmaHurricane2017



Sentinel-1

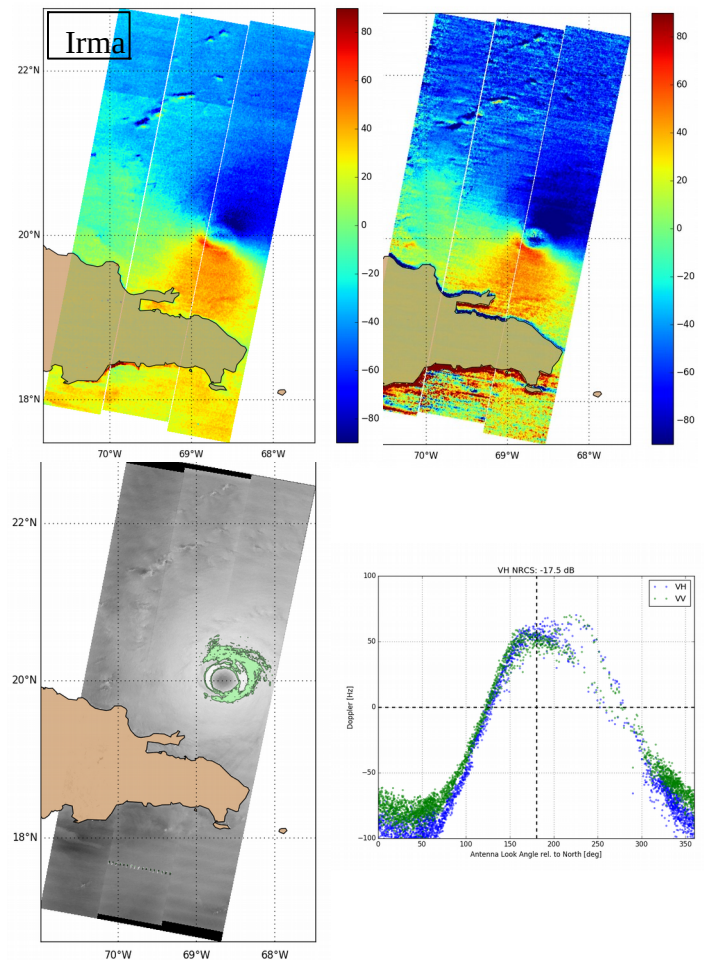
Contains modified Copernicus
Sentinel data (2017)

As for Envisat/ASAR, Sentinel-1 A & B are the only missions able to routinely provide Doppler anomalies.

In addition, Sentinel-1 SAR provide Doppler at 1 km and in both VV and VH polarizations.

First analysis of data acquired over hurricane reveal that:

- Doppler in VV and VH have a very similar behaviour
- They do not saturate at high winds reaching Doppler values larger than 100 Hz
- They are very sensitive to the wind direction relative to the antenna



Wave Doppler (bias)

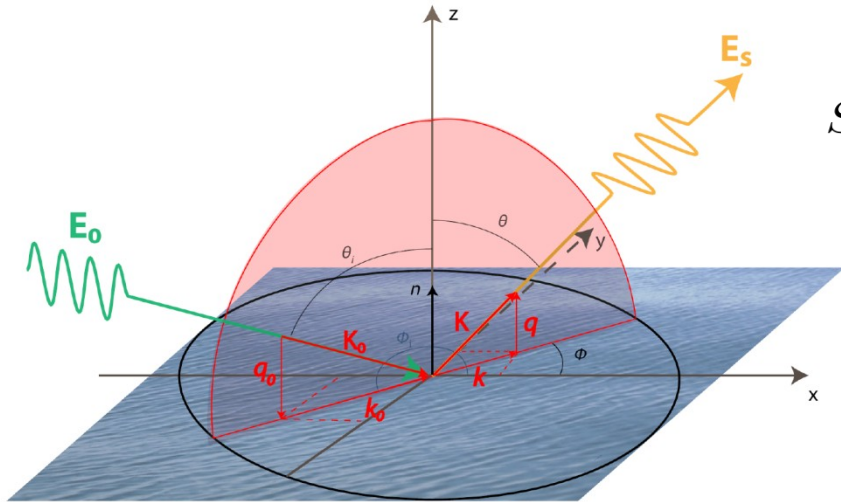


Figure 5: Diffraction (S. Guimbard)

$$S_{KA}(t) \propto \frac{\kappa e^{iK(R-ct)}}{Q_z (2\pi)^2} \int_A d\mathbf{r} e^{i\mathbf{Q}_H \cdot \mathbf{r}} e^{iQ_z \dot{\eta}(\mathbf{r}, t)}$$

$$\mathbf{Q}_H = \mathbf{k} - \mathbf{k}_0$$

$$Q_z = q + q_0$$

✓ **Sea-state Doppler frequency**

$$f_{GD} = \frac{Q_z}{2\pi} \left(\underbrace{mss_{xt}}_{\text{Mean range slope-velocity cross-correlation}} \cdot \underbrace{\frac{\partial_{\tan \theta} \psi^0}{\psi^0}}_{\text{NRCS incidence rate of variation}} + \frac{mss_{yt}}{\tan \theta} \cdot \underbrace{\frac{\partial_{\phi} \psi^0}{\psi^0}}_{\text{NRCS azimuthal rate of variation}} \right)$$

Mean range slope-velocity cross-correlation

NRCS incidence rate of variation



Mean azimuth slope-velocity cross-correlation

NRCS azimuthal rate of variation

A quick focus on the equations

✓ Sigma0 modulations (basic RAR concept equation):

$$\tilde{\sigma}^0(x) = \sigma^0 \left(1 + \frac{\partial_x \eta_l(x)}{\sigma^0} \frac{\partial_{\tan \theta} \sigma^0}{\sigma^0} \right)$$

Range resolved
 wave slopes
 wave velocity

✓ Doppler (velocity) modulations (basic Doppler equation):

$$2\pi \widetilde{f_{GD}}(x) = Q_z \frac{\partial_t \eta_l(x)}{\sigma^0} + \frac{Q_z m_{SSxt}}{\tilde{\sigma}^0(x)} \left[\partial_{\tan \theta} \sigma^0 + \frac{\partial_x \eta_l(x)}{\sigma^0} \frac{\partial_{\tan^2 \theta}^2 \sigma^0}{\sigma^0} \right]$$

✓ Weighted Doppler modulations :

$$2\pi \frac{\tilde{\sigma}^0(x) \widetilde{f_{GD}}(x)}{\sigma^0} = Q_z \frac{\partial_t \eta_l(x)}{\sigma^0} + Q_z m_{SSxt} \frac{\partial_x \eta_l(x)}{\sigma^0} \frac{\partial_{\tan^2 \theta}^2 \sigma^0}{\sigma^0} + \dots$$

